

MODEL 282L ONE INCH FULL PIPE SENSOR

INSTALLATION AND PROFILING MANUAL

JULY 2010

PATENT NOTICE

This equipment is manufactured under one or more of the following U.S. Patents: 4083246; 4549434; 4459858

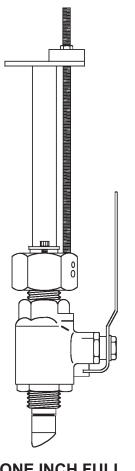


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ABOUT THIS MANUAL

The purpose of this manual is to provide the information necessary to install the one inch full pipe sensor and profile the flow. Along with this manual you will need an installation and operations manual for the flowmeter.



ONE INCH FULL PIPE SENSOR AND INSERTION HARDWARE

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SAFETY SUMMARY

The following are general safety precautions that are not related to any specific procedure and therefore do not appear elsewhere in this publication. These are the recommended precautions that personnel must understand and apply when working in confined spaces. Examples of confined spaces are boilers, furnaces, degreasers, pipelines, pits, pumping stations, septic tanks, sewage digesters, manholes, vaults, and storage tanks.

NEVER ENTER A CONFINED SPACE WITHOUT TESTING THE AIR

The air inside confined spaces may be toxic, oxygen deficient, or explosive due to a lack of good ventilation. This is because most confined spaces are not designed for workers to enter and work on a routine basis.

Do not trust your senses to determine if the air in a confined space is safe. You cannot see or smell many of the toxic gases or vapors. Test the space at the bottom, middle, and top.

NEVER ENTER A CONFINED SPACE WITHOUT THE PROPER SAFETY EQUIPMENT

Do not enter a confined space without the proper safety equipment such as a tripod, lifeline, and gas detector.

NEVER ENTER A CONFINED SPACE WITHOUT STANDBY/RESCUE PERSONNEL

Only enter a confined space in the presence of someone who is capable of rendering aid. Standby personnel should not have any other duties but to serve as standby and know what action to take in case of an emergency. Standby personnel should not enter a confined space until help arrives and then only with proper equipment, life lines, and respirators.

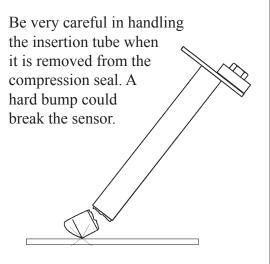
Comment:

Over 50% of workers who die in confined spaces are attempting to rescue other workers.

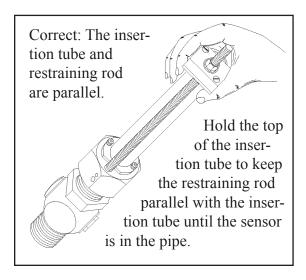
SENSOR HANDLING

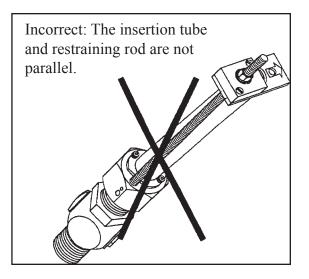
To avoid damaging the sensor, observe the following rules when handling the insertion hardware:

- If the sensor is removed from the insertion tube, use twice the amount of Teflon tape on the sensor threads as you would normally use on pipe threads when it is put back on the insertion tube.
- In positioning the sensor at the far wall of the pipe, be careful. Do not jam the sensor into the far wall or force the captive nut when the sensor stops.



- Never force the sensor. If you feel any resistance or scraping, stop immediately and retract the sensor. Eliminate the source of the resistance before you try to reinsert the sensor.
- Make sure the corporation stop is completely open. A partially open corporation stop will scrape the side of the sensor and require sensor replacement.
- The top opening and bottom opening of corporation stops are not concentric. The result may be the sensor scraping the inside of the corporation stop. Consult the factory before you attempt to install the sensor into existing corporation stops.





SPECIFICATIONS

VELOCITY MEASUREMENT

METHOD: Electromagnetic (Faraday's Law) RANGE: -0.5 to +20 ft/sec (600 cm./sec) ACCURACY: ± 2% of reading, ± zero stability ZERO STABILITY: ±0.03 ft/sec

MATERIALS

SENSOR: Polyurethane exposed to flow SENSOR CABLE: Twinax Polyurethane outer jacket SENSOR MOUNTING: 316 stainless steel exposed to flow

PRESSURE / TEMPERATURE LIMITSINSERTION TUBE: 250 psi @ 160° F

SENSOR: Flow temperature range 32° F to 160° F (0° C to 72° C) at 250 psi. Sensors for extreme environments are available, subject to application review - contact factory.

DIMENSIONS

SENSOR: .937" Diameter (Requires 1" ball valve port clearance) INSERTION HARDWARE: .937" Diameter, Lengths 12", 24", and 36"

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SECTION I

GENERAL DESCRIPTION

Sensor

The one inch full pipe sensor (Figure 1-1) measures water velocity in full pipes. The sensor operates on the Faraday principle which states that a conductor moving through a magnetic field produces a voltage that is directly proportional to the velocity of the conductor. An inductor inside the sensor produces the magnetic field, and two velocity electrodes on the surface of the sensor measure the voltage produced by the water (moving conductor). The flowmeter electronics convert the voltage measurement to a velocity output. *Comment:*

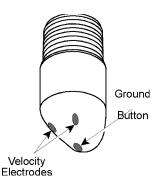


Figure 1-1. Sensor

The purpose of the reference electrode is to suppress electrical noise that may be present in the water.

Insertion Hardware

The insertion hardware (Figure 1-2) consists of a sensor, sensor cable, ball valve, and insertion tube. The sensor is attached to the insertion tube and the insertion tube is inserted into the pipe through a 1" ball valve or corporation stop. A standard sensor cable is 20 feet long and terminates at a terminal strip or sensor disconnect.

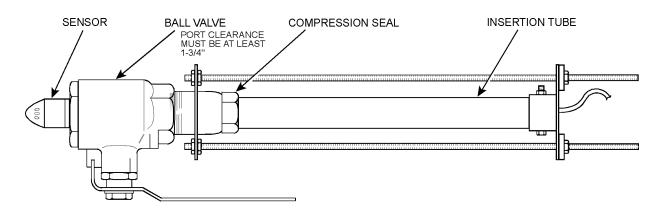


Figure 1-2. Insertion Hardware

Flow Measurement

Velocity Profile

The velocity profile is the velocity of the water at various positions on a plane across the pipe. These velocities vary and the slowest velocities are at or near the pipe wall. The result is a profile shape similar to the one shown in Figure 1-3. This shape is referred to as the theoretical profile.

Comment:

Pipe elbows, valves or obstructions will cause the profile shape to change.

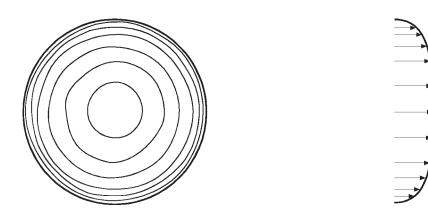


Figure 1-3. Velocity Profile (Theoretical)

Mean Velocity

The mean velocity (\overline{U}) is the average of all the velocities across the flow.

Sensed Velocity

The sensed velocity (U) is the velocity that is measured by the sensor which is located near the sensor electrodes.

Flow Calculation

Flow is calculated with the continuity equation $Q = \overline{U}x A$ where Q is flow, \overline{U} is mean velocity and A is cross-sectional area of the pipe.

Velocity Multipliers (K1, K2, K3)

The velocity multiplier (K) modifies the sensed velocity so that it can be used as the mean velocity in the continuity equation. One velocity multiplier (K1) is a first order multiplier and a first order multiplier assumes a linear relationship between the sensed velocity and the velocity profile. This may be significantly non-linear when:

- The difference between the minimum and maximum flow is three or more times.
- The sensor is located near an elbow, junction, or obstruction.

If the above conditions exist, a second or third order multiplier is appropriate. The third order equation is:

 $U = K_1 U_s + K_2 U_s^2 + K_3 U_s^3$

Where (K) is the multiplier and (U_s) is the sensed velocity.

Calculating the Velocity Multipliers

We must have a sensed velocity and a mean velocity to calculate the velocity multiplier. Profiling is the method we use to get the mean velocity. When the flow is profiled, the velocity is measured at various locations across the flow.

Comment:

A second order multiplier requires at least three profiles and a third order multiplier requires at least four profiles. The profiles should be evenly spaced over the range of flows and must include a profile of the minimum and maximum flow rates.

You will need the Flow Calculator software package to calculate second or third order multipliers. Factory assistance is also available.

Check the instruction manual for your model flowmeter to see if the meter can use second and third order multipliers.

Calculating the Mean Velocity

The pipe cross-section is divided into a number of concentric rings called annular areas (Figure 1-4). Although the velocity across the pipe changes, the velocity in a particular annular area is considered constant. Each annular area velocity is weighted because the amount of influence that each one has on the mean velocity calculation is different. To get the mean velocity, the weighted velocities are totaled then they are divided by a mean velocity factor.

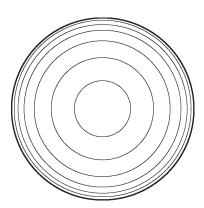


Figure 1-4. Annular Areas

The two inch profiling data log in the back of this manual has a column of sensor locations. Each location in this column represents an annular area. The velocity at each location is measured with the sensor and recorded in the log. The velocity at a particular location is multiplied by the weighting factor at that location. The weighted velocities are totaled and divided by the mean velocity factor at the bottom of the log to get the mean velocity.

Isotachs

An isotach indicates a velocity gradient (Figure 1-5). This can be compared to a topographic map that shows the varying terrain with elevation lines. Notice that the isotachs in Figure 1-5 are concentric circles. These isotachs are from a fully developed profile in a straight run of pipe. This is the configuration that was used to develop the weighting factors in the profiling data log. The best results are attained in applications which have velocity profiles similar to the one used to develop the information in the profiling data log.

Sensor Location

Locate the sensor as far as possible away from elbows, valves, and junctions. A few guidelines are as follows:

Figure 1-5. Isotachs

• The sensor should be located at least 5 pipe diameters upstream or 10 pipe diameters downstream from elbows and junctions.

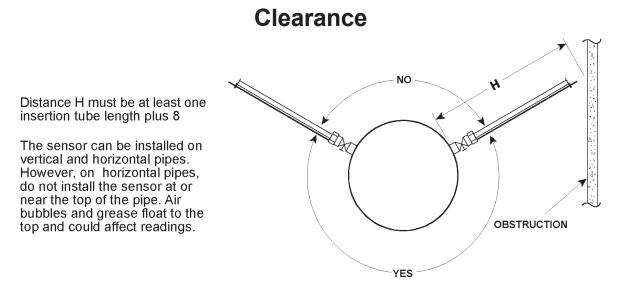
Comment:

The best results are obtained from a sensor that is as far as possible away from elbows, junctions, and obstructions.

• The sensor must be located at least 10 pipe diameters upstream or 25 pipe diameters downstream from active valves.

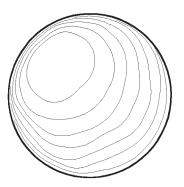
SECTION II APPLICATION SCHEMATICS

The application schematics (Pages 2-1 to 2-7) show different applications and the best sensor location for a particular application.

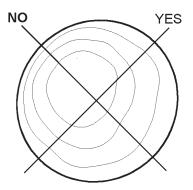


Skewed Profiles

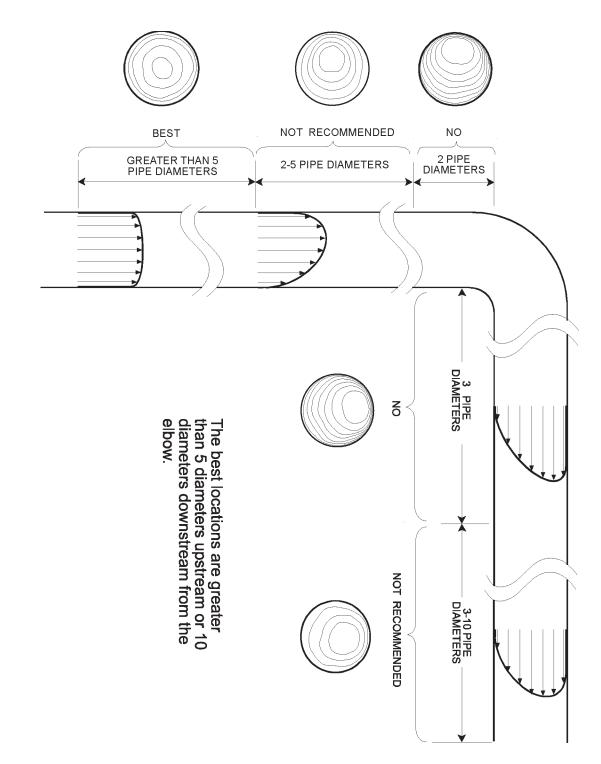
This profile is skewed too much to get good results. These locations are indicated by a NO in the application schematics.



This profile is somewhat skewed. These locations, which are indicated by a NOT RECOMMENDED in the application schematics, should be avoided.



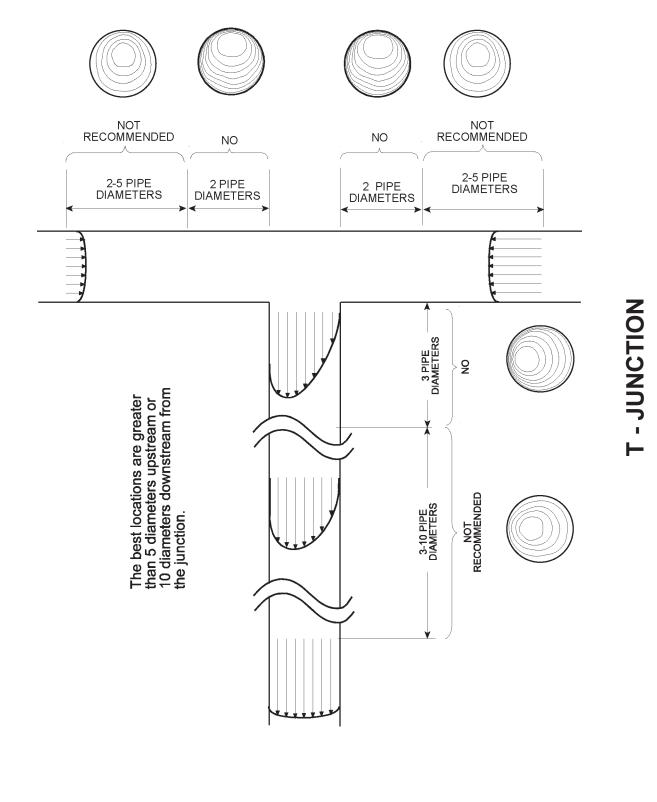
If a NOT RECOMMENDED location cannot be avoided, mount the sensor so that the profile is bisected asymmetrically when the pipe is traversed.



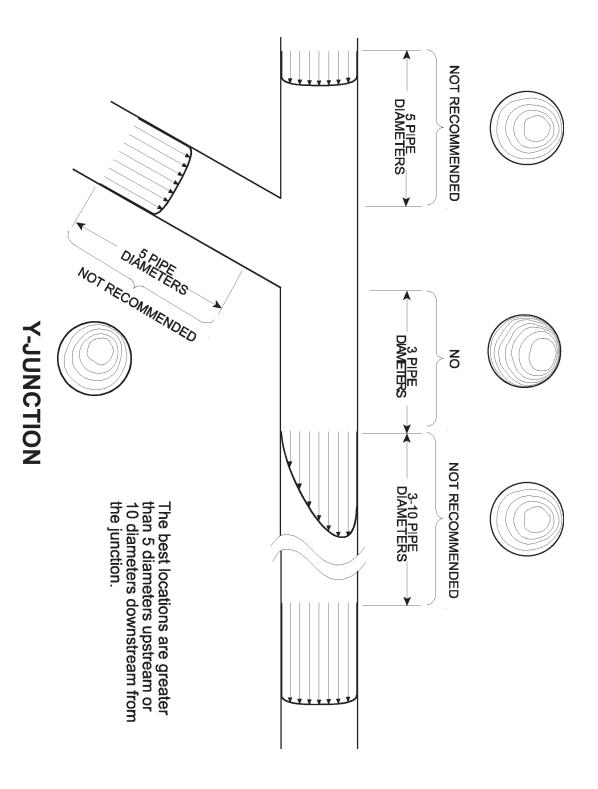
90° ELBOW

2-2

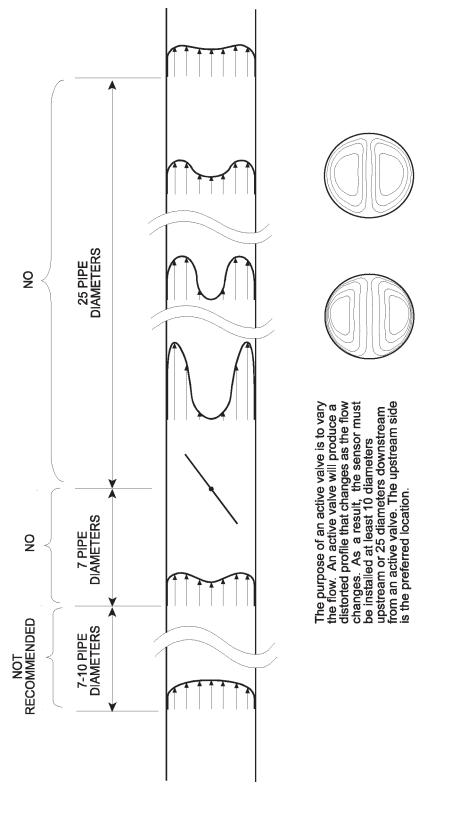
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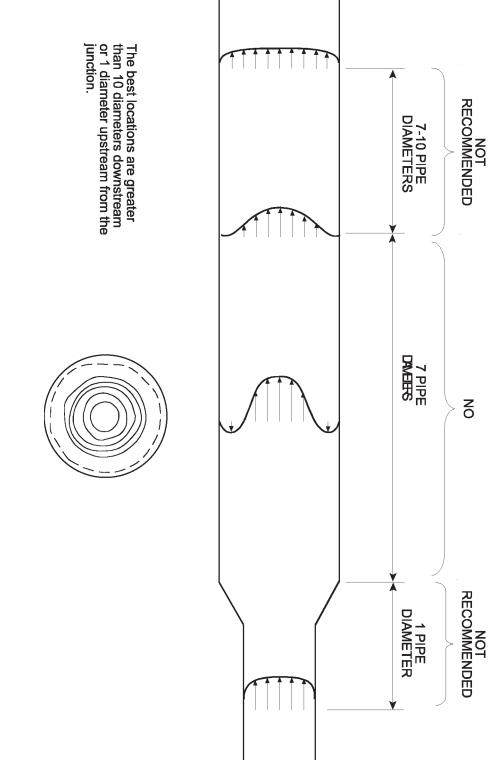


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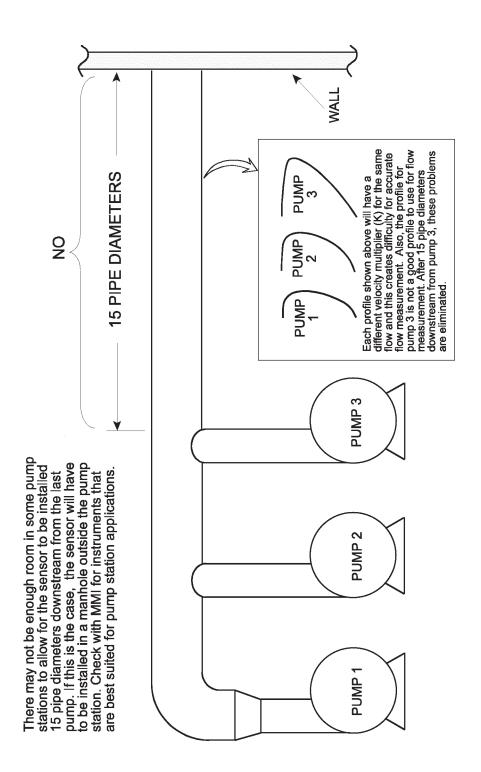
ACTIVE VALVES

2-5





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PUMP STATION

SECTION III INSTALLATION AND PROFILING

This instruction is for the installation of the sensor and insertion hardware. The sensor cable connections and flowmeter installation instructions are contained in the manual for your model flowmeter. The installation outline is as follows:

- Mount the flowmeter electronics.
- Install the sensor.
- Measure the inside diameter of the pipe.
- Profile the flow.
- Calculate Mean Velocity (\overline{U}) .
- Set the sensor at the operating position.
- Record the velocity at the operating position.
- Calculate the Velocity Multiplier.

INSTALLATION

Flowmeter

Install the flowmeter as described in the technical manual for your model flowmeter.

Sensor

Location, Position, and Clearance

The Application Schematics (Pages 2-1 through 2-7) illustrate sensor location, position, and clearance requirements.

Access Hole

The pipe must be tapped and have a pipe nipple in place before the sensor can be installed. A smooth 1" access hole (Figure 3-1) and a flush pipe nipple (Figure 3-2) are required for accurate flow measurement in waste water applications. Clean water applications that can use the 1/8 D operating position do not have to have flush pipe nipples.

WARNING

Tapping into pressurized pipes is dangerous and injury could result from improper tapping procedures.

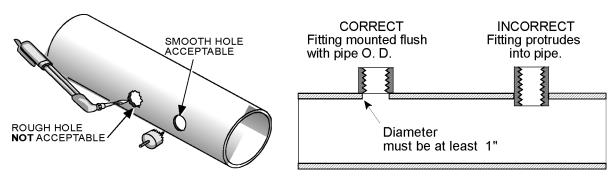


Figure 3-1. Access Hole

Figure 3-2. Pipe Nipple

Check Sensor Alignment

The sensor, insertion tube, and compression seal are shipped as an assembled unit. To check sensor alignment:

• Remove the insertion tube and restraining rod from the compression seal.

Comment:

Exercise care in handling the sensor and insertion tube (Sensor Handling Page i).

The sensor should not have to be removed from the insertion tube. If the sensor needs to be removed, call the factory.

• Check sensor alignment (Figure 3-4). If the sensor needs to be aligned, use a strap wrench (Figure 3-3) to rotate the sensor. Do not force the sensor or use other types of wrenches.

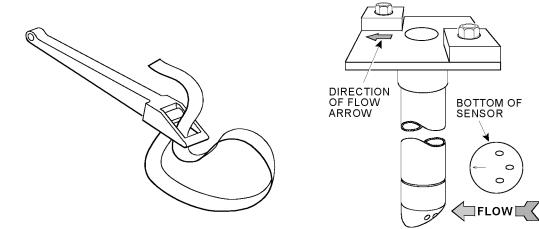
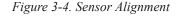


Figure 3-3. Strap Wrench



0

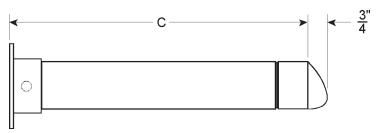


Figure 3-5. Length C

Measure Length C

Measure and write down length C. This is measured from the top edge of the insertion tube cap to the start of the tapered section on the sensor (Figure 3-5). You will need this measurement to do the profile.

RESTRAININ G PLATE RESTRAININ G PLATE RESTRAINING ROD HOLE

Figure 3-6. Compression Seal Installation

Install the Compression Seal

Install the ball valve on the pipe nipple. Use teflon tape to seal the pipe threads. Do not use pipe dope because the unit will only output near zero velocity readings if pipe dope gets on the sensor electrodes.

- Remove the plastic cover from the pipe nipple on the compression seal and wrap the nipple with teflon tape.
- Screw the compression seal into the ball valve. The restraining rod holes need to be oriented so that they form a line that is parallel to the side of the pipe (Figure 3-6).
- Put the insertion tube back in the compression seal and reinstall the restraining rod. Do not extend the sensor beyond the nipple.
- Check the restraining rod at the compression seal for proper installation. The set screw must be flush with the surface. The flat portion of the restraining rod must be viewed through the inspection hole (Figure 3-7).

WARNING

The insertion tube may shoot out of the pipe if the restraining rod is not properly installed.

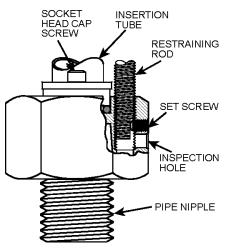


Figure 3-7. Compression Seal

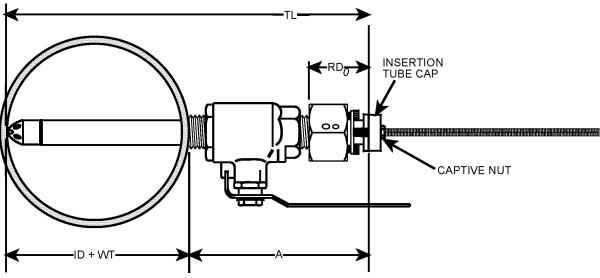


Figure 3-8. Checking Pipe ID

IMPORTANT

Tighten the socket head cap screws on the compression seal (Figure 3-7) only enough to seal the insertion tube. Tightening the screws too much may cause the seal to grip the insertion tube. This could result in the captive nut (Figure 3-8) being pulled out of the insertion tube cap when the insertion tube is retracted from the pipe.

Check Pipe ID

If you do not know the inside diameter (ID) and wall thickness (WT) of the pipe, measure them before you start to profile. The best method is to measure them directly; however, if the flow cannot be shut down, the sensor can be used to get these measurements.

- Carefully insert the sensor through only the compression seal.
- Open the ball valve.
- Place a 9/16" box ratchet on the captive nut, and rotate clockwise until the tip of the sensor reaches the far wall of the pipe. The sensor will stop and you will not be able to turn the ratchet.

CAUTION

As the sensor nears the far wall, slow down and do not force the ratchet. Excessive force could damage the sensor and insertion hardware which would require sensor replacement.

- Measure the outside circumference of the pipe and divide this measurement by (3.14). This is the outside diameter (OD).
- Add 1/2" to length C (Figure 3-5). This is total length (TL).
- Measure distance A (Figure 3-8). This is measured from the pipe OD the top edge of the insertion tube cap .
- Subtract distance A from total length (TL). This will give the inside diameter (ID) plus one wall thickness (WT).

TL - A = ID + WT

• Determine the wall thickness by:

WT = OD - (ID + WT)

• Determine inside diameter by:

ID = OD - 2(WT) or ID = (ID + WT) - WT

Measuring the Velocity Profile

Far Wall Method

The far wall is the wall opposite the sensor mounting hardware. The far wall method starts with the first velocity measurement being taken at the far wall. If the insertion tube is too short to traverse the pipe, use the near wall method (Page 3-9) to do a partial profile (Section IV).

Comment:

The far wall method is preferred because it is easier to locate the far wall than it is the near wall.

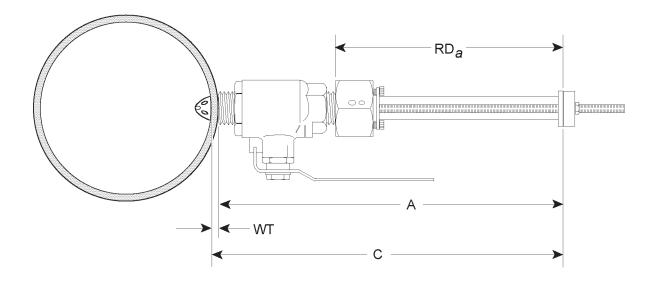
The sensor cable must be connected to the flowmeter and the meter must be set to output velocity. Check the flowmeter instruction manual for sensor cable connection and velocity output.

To obtain the velocity profile, you will need to measure multiple velocities at various locations across the pipe. To do this you need:

A reference distance (RD).

The profiling data log at the back of this manual.

The reference distance is measured from the top edge of the insertion tube cap to the bottom edge of the compression seal nut (Figure 3-9).



- Make a copy of the page in the profiling data log that is marked with the inside diameter (ID) of your pipe.
- Position the sensor at the far wall (RD₀) by rotating the captive nut on the insertion tube cap clockwise until the sensor stops (Figure 3-8). Slow down as the sensor approaches the far wall and do not force the ratchet.

	PIPE ID = 2.25"		2.25" # O	F DATA POINTS 6
	· · ·		MEASURED VELOCITY (FPS)	WEIGHT WEIGHTED CONSTANT VELOCITY
RD₅		0.00 0.25 0.50		x 2.771 = x 0.598 = x 0.249 =
		0.75 1.00 1.50		x 0.083 = x 0.613 = x 1.717 = TOTAL
Ũ	ΤΟΤΑ	\L	_ ÷ 6.52 = MEA	N VEL

Comment:

The profiling data log is in the back of this manual. Make a copy of the appropriate page and use the copy to do the profile.

Figure 3-10. Profiling Data Log

- Measure (RD₀) and write it down in the bottom of the (RD) column.
- Rotate the captive nut on the insertion tube cap counter-clockwise until (RD₁) is reached.

 $RD_1 = (RD_0 + 1/4")$

- Record (RD₁) and the velocity reading in the appropriate columns at the bottom of the log at (RD₁) location (Figure 3-10).
- Position the sensor at (RD_2) . Record (RD_2) and the velocity. $RD_2 = (Sensor \ Location \ RD_1 - Sensor \ Location \ RD_2) + RD_1$
- Position the sensor at (RD₃). Record (RD₃) and the velocity.

 $RD_3 = (Sensor \ Location \ RD_2 - Sensor \ Location \ RD_3) + RD_2$

• Repeat this until you reach sensor location 0.00.

Sensor Location Check

The sensor location check is used to verify the pipe ID. With the sensor at location 0.00, increase distance (RD) by 1/2". This should retract the sensor into the ball valve and cause the velocity to drop to zero. If the velocity is not zero, then the ID is larger than thought. If the velocity drops to near zero before location 0.00 is reached, the ID is smaller than thought.

Mean Velocity (\overline{U}) Calculation

After you have finished profiling, you need to calculate the mean velocity (\overline{U}) .

- Multiply each measured velocity by the weight constant and record the product in weighted velocity column.
- Now add the weighted velocities and record the total in the TOTAL block.
- Divide the total by the number specified on the bottom of the log to find the mean velocity.

Velocity Multiplier (K1, K2, K3)

The Velocity Multiplier (K) converts the sensed velocity to a mean velocity. For all flowmeters that use the Flo-Ware program, the velocity multiplier is calcualted by that program. Check the Flo-Ware Communications User manual for a description of the velocity multiplier fields. For those flowmeters which do not use the Flo-Ware program, the velocity multiplier calculation is as follows:

- Position the sensor at the operating position and record the velocity.
- Divide the mean velocity that was recorded in the profiling data log by the operating position velocity. The result is Velocity Multiplier (K).

Comment:

If you want to do a second or third order correction (Page 1-3), you must use the Site-Ware program. You can also consult the factory.

The flow at the time the profile is done and the flow at the time the velocity multipliter is calculated must be the same.

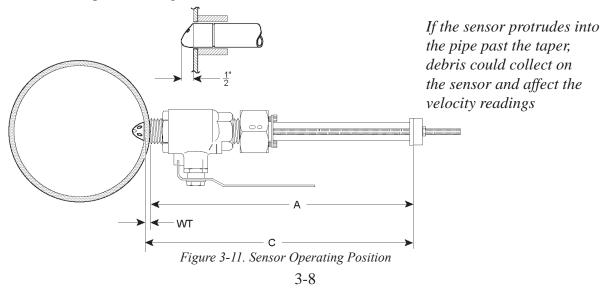
Sensor Operating Position (Raw Waste Water)

The operation position for raw waste water and sludge is at sensor location 0.00. To position the sensor at this location you need to:

- Calculate distance A (Figure 3-11) by subtracting the pipe wall thickness (WT) from length C (Figure 3-5).
- Position the top edge of the insertion tube cap distanced A (Figure 3-11) from the pipe.

Sensor Operating Position (Clean Water)

The preferred operating position for clean water that does not contain rags or strings is at the 1/8 D sensor position (Page 3-12).



Measuring the Velocity Profile

Near Wall Method

The near wall is the wall through which the sensor enters the pipe. With the near wall method, the first velocity measurement is taken when the sensor is located at the near wall.

Comment:

The far wall method is preferred because it is easier to locate the far wall than it is the near wall.

The sensor cable must be connected to the flowmeter and the meter must be set to output velocity. Check the flowmeter instruction manual for sensor cable connection and velocity output.

To measure the velocity profile, you will need to measure the velocity at various locations across the pipe. To do this you need:

A reference distance (RD).

The profiling data log at the back of this manual.

The reference distance is measured from the top edge of the insertion tube cap to the bottom edge of the compression seal nut (Figure 3-12).

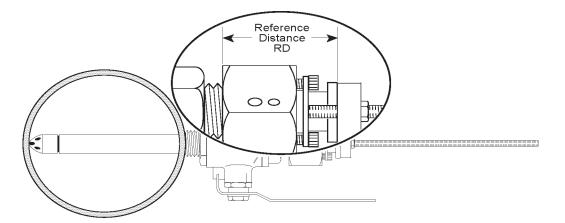


Figure 3-12. Reference Distance RD

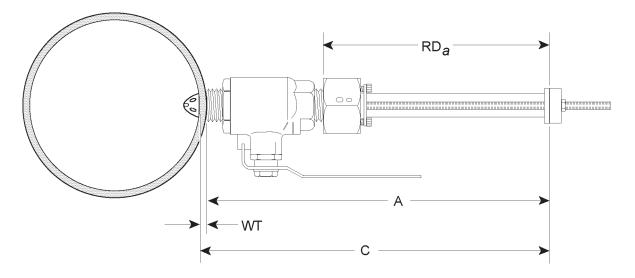
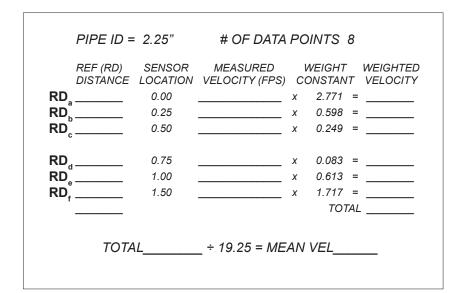


Figure 3-13. RD_a Near Wall

- Make a copy of the page in the profiling data log that is marked with the inside diameter (ID) of your pipe.
- Calculate distance A (Figure 3-11) by subtracting the wall thickness (WT) from length C.
- With a ratchet, rotate the captive nut on the insertion tube cap until the top edge of the insertion tube cap is distance A from the pipe. This is sensor position RD_a.
- Measure reference distance RD_a (Figure 3-13) and record it at sensor location 0.00 under the reference distance column in the profiling data log (Figure 3-14).
- Record the velocity in the Measured Velocity column next to sensor location 0.00.
- Calculate RD_b and rotate the captive nut clockwise until RD_b is reached.
 RD_b = RD_a (Sensor Location RD_b Sensor Location RD_a)
- Record RD_b and the velocity in the appropriate columns.
- Calculate RD_c and rotate the captive nut clockwise until RD_c is reached. $RD_c = RD_b$ - (Sensor Location RD_c - Sensor Location RD_b)
- Record RD_c and the velocity in the appropriate columns.
- Repeat this until you reach the bottom sensor location.



Comment:

The profiling data log is in the back of this manual. Make a copy of the appropriate page and use the copy to do the profile.

Figure 3-14. Profiling Data Log

Sensor Location Check

The sensor location check is used to verify the pipe ID. After you have reached the bottom location, decrease distance RD by 1/4". The sensor should stop. Do not force the captive nut. If the sensor stops before the 1/4" distance is reached, then the ID is smaller than thought. If the sensor does not stop when the 1/4" distance is reached, then the ID is larger than thought.

Comment:

A mistake in sensor positioning during the profile could also produce errors. Make sure the sensor is in the proper positions when profiling.

CAUTION

Do not force the captive nut. This could damage the sensor and insertion hardware.

Mean Velocity (\overline{U}) Calculation

After you have finished profiling you need to calcualte the mean velocity.

• Multiply each measured velocity by the weight constant and record the product in the Weighted Velocity column.

- Add the weighted velocities and record the total at the bottom of the page in the TOTAL block.
- Divide the total by the number specified on the bottom of the log to find the mean velocity.

TOTAL_____ ÷ XX.XX = MEAN VEL

Velocity Multiplier (K1, K2, K3) Calculation

Calculate the velocity multiplier as described on Page 3-7.

Sensor Operating Position

The operating position for raw waste water and sludge is at sensor location 0.00 (Page 3-8). The operating position for clean water is at the 1/8 D position (Page 3-12).

1/8 D Profile

The accuracy of a 1/8 D profile depends on the existence of a theoretical profile (Page 1-2), and should only be used when the profile is symmetrical or like the theoretical. An industry accepted standard is that the velocity of the flow at a distance of 1/8 the diameter from the wall of the pipe is considered to be the mean velocity. To profile, simply position the sensor at 1/8 D and record the velocity. Then calculate the velocity multiplier (Page 3-7).

1/8 D Sensor Position

• Find Tube Length (TL)(Figure 3-15).

$$TL = C + \frac{1}{2}$$

• Calculate (1/8 D).

$$\underline{D}_{s}$$
 = .125 x Pipe ID

- Add wall thickness to 1/8 D.
- Calculate distance A (Figure 3-16).

A = TL - (1/8 D + WT)

The tip of the sensor will be at 1/8 D.

Figure 3-15. Tube Length (TL)

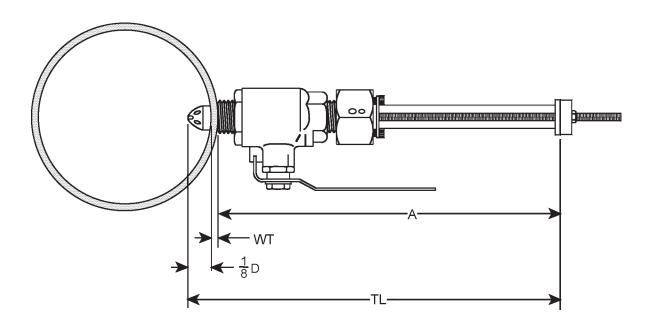


Figure 3-16. 1/8 D Sensor Position

- Set the top edge of the insertion tube cap distance (A) from the pipe.
- Record the velocity and calculate the velocity multiplier (Page 3-7).

If the flow is clean water, the sensor can be left at the 1/8 D position. At this position, the sensed and mean velocity are equal and K = 1. Do not leave the sensor in this position for raw waste water because debris could collect on the sensor and affect the velocity readings. In waste water applications, position the sensor at location 0.00 (Page 3-8).

OPTIONS

Cable Disconnect Option

The cable disconnect is used on both the sensor and pressure cables. To connect the cable, align the latch alignment marks and push the connector together. To disconnect the cable, pull the latch release toward the cable.

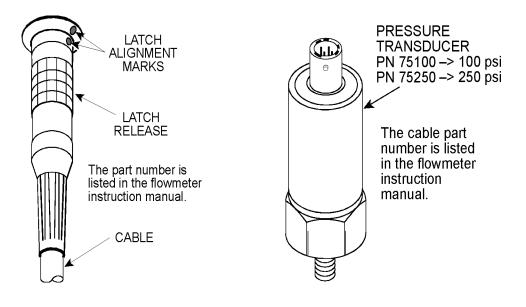


Figure 3-17. Cable Disconnect

Figure 3-18. Pressure Transducer

Comment:

The cable disconnect is not available on all flowmeters.

Pressure Options

The 1" full pipe sensor insertion hardware can be configured with a 100 psi pressure transducer.

Comment:

The pressure option is not available on all instruments. If the option is available, the instrument instruction manual will contain the information that describes how to connect the pressure cable to the flowmeter.

Pressure transducer installation.

- Retract the sensor past the ball valve and close the valve.
- Remove the plug in the pressure port (Figure 3-17) on the compression seal.
- Wrap the pressure transducer threads with teflon tape and screw into the pressure port.
- Connect the cable to the pressure transducer and flowmeter.
- Open the ball valve and position the sensor at the operating position.

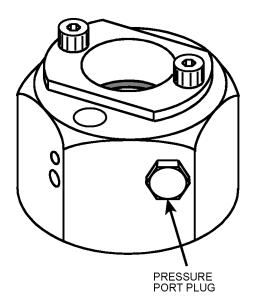
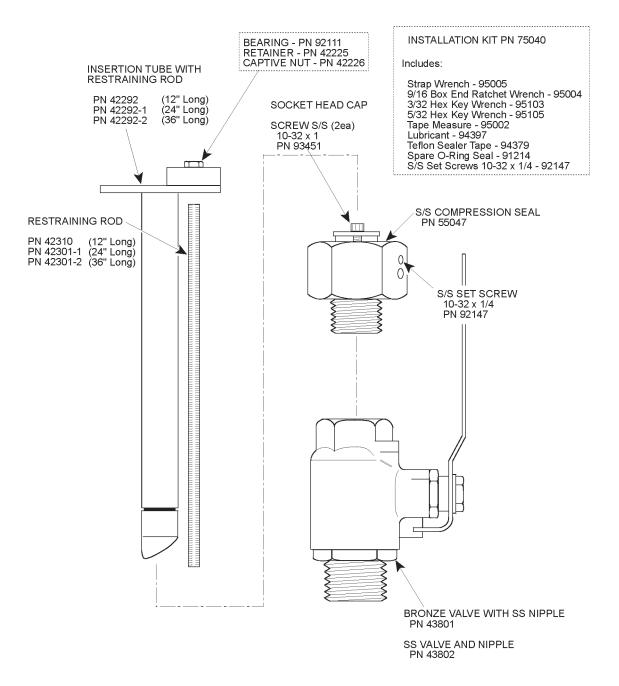


Figure 3-19. Pressure Port



ONE INCH FULL PIPE SENSOR PARTS ILLUSTRATION

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SECTION IV

PARTIAL PROFILES

In an application where it is difficult to measure a complete velocity profile, a partial profile can be used to estimate a complete profile. The mean velocity can then be calculated from the estimated profile. The accuracy of this technique however, is dependent upon experience with fluid dynamics. Do not use the partial profile as a substitute for the complete profile. Use the partial profile when:

- The insertion tube is too short to traverse the pipe.
- A constant flow rate cannot be maintained long enough to do a full profile.
- The combination of a long insertion tube and high velocity causes excessive sensor vibration.

Partial profiling requires that the user be familiar with the type of profiles that can be expected when the sensor is inserted into a pipe (Figure 4-1). Elbows or obstructions cause distorted profiles and make estimation difficult. This problem can be avoided by locating the sensor a distance of five diameters upstream or ten diameters downstream from obstructions or elbows.

Notice that the expected profile is not symmetrical about the center line. The insertion tube partially

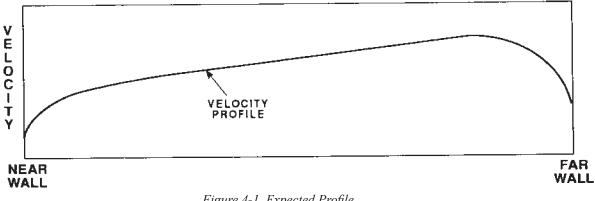


Figure 4-1. Expected Profile

obstructs the conduit causing the fluid to speed up. The speeding up effect is less noticeable in the larger diameter conduits.

Partial Profiling Methods

Every other point method:

Measure and record the point velocity at every other sensor location (See profiling data log for sensor location values). This will cut the profiling time in half.

60% method:

Measure and record the point velocities across 60% of the pipe diameter.

Combination method:

Measure and record the point velocity at every other sensor location across 60% of the pipe diameter.

Profile Curve Estimation

To estimate the profile, you need to:

- Measure the partial profile and record these velocities in the profiling data log. As a minimum, try to traverse 60% of the pipe diameter at every other sensor location. The more points you measure, the easier it will be to estimate the profile curve.
- Plot the measured velocities on a graph. Mark the vertical axis velocity and the horizontal axis sensor location.
- Calculate far/near wall velocity.
- Draw a smooth curve connecting the near and far wall velocities. Use the partial profile and the expected profile to estimate the profile curve.
- Find the missing velocities on the curve and record them in the profiling data log.

With either the far wall (Page 3-5) or near wall (Page 3-9) profiling method, measure as many point velocities as you can and plot them on a graph (Figure 4-2).

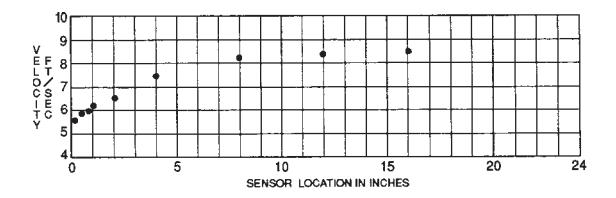


Figure 4-2. Partial Profile Plot (24" Diameter)

Far/Near Wall Sensor Location Velocities

There is approximately an 18% difference between the far wall and near wall sensor location velocities. The far wall velocity is faster than the near wall velocity. Calculate by:

- 1.18 x near wall velocity = far wall velocity.
- 0.85 x far wall velocity = near wall velocity.

Plot the far/near wall sensor location velocity points.

Complete The Profile Curve

Draw a continuous curve of the complete profile. Estimate the curve where the velocity points are missing. The estimation is based on the expected profile (Figure 4-3).

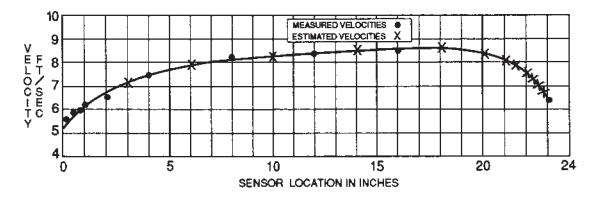


Figure 4-3. Complete Profile Curve (24" Diameter)

Notice that the curve does not cover the complete diameter of the pipe. This is because the sensor locations in the profiling data log are used as points of reference to plot the estimated curve. Actual velocity position is from 0.75" to 23.75".

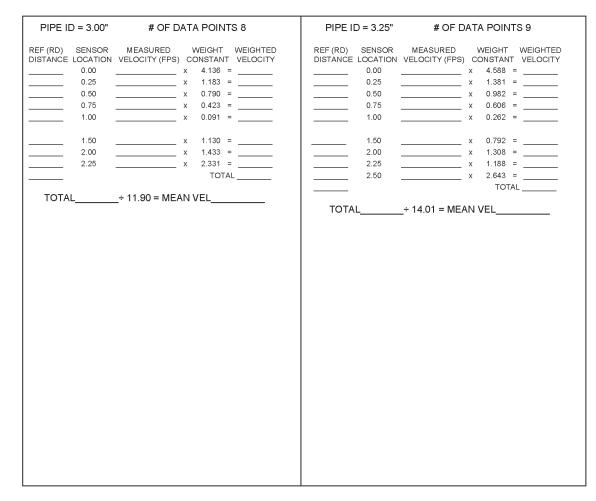
Find the missing velocity points on the profile curve. From the graph, read the velocity values at these points and record them in the profiling data log. You may want to highlight the estimated velocity values for future reference. Calculate the mean velocity as described on Page 3-7.

PIPE ID = 2.00" # OF DATA POINTS 5	PIPE ID = 2.25" # OF DATA POINTS 6
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR MEASURED WEIGHT WEIGHT WEIGHT DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY 025 X 0.598 =

2.00 - 2.25

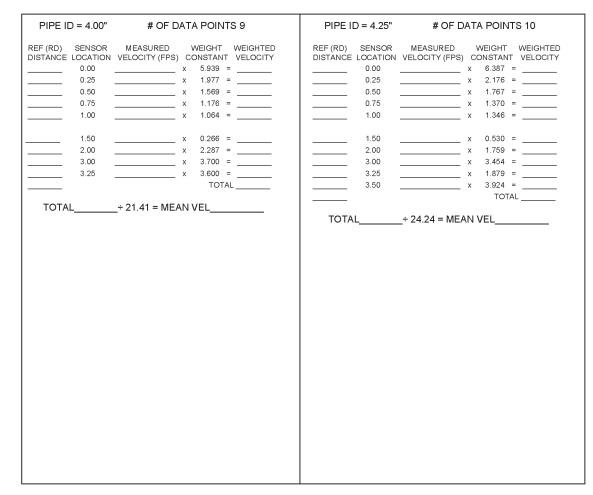
PIPE ID = 2.50" # OF DATA POINTS 7	PIPE ID = 2.75" # OF DATA POINTS 8
REF (RD) SENSOR MEASURED WEIGHT WEIGHT DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	PIPE ID = 2.75 # OF DATA POINTS 6 REF (RD) SENSOR MEASURED WEIGHT 0.00 X 3.683 =

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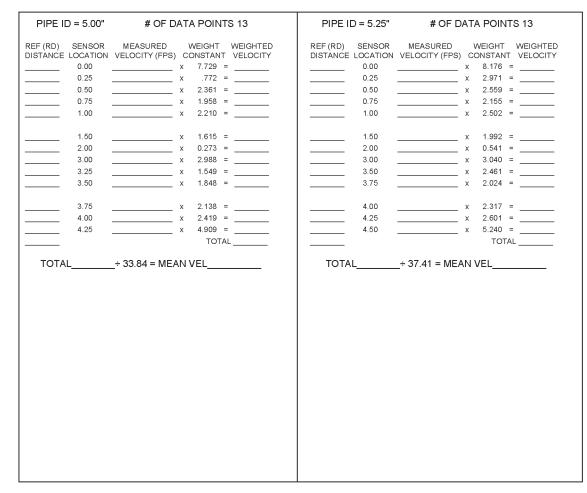
PIPE ID = 3.50" # OF DATA POINTS 10	PIPE ID = 3.75" # OF DATA POINTS 11
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED 0.00	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED 0.00 x 5.489 =

3.50 - 3.75



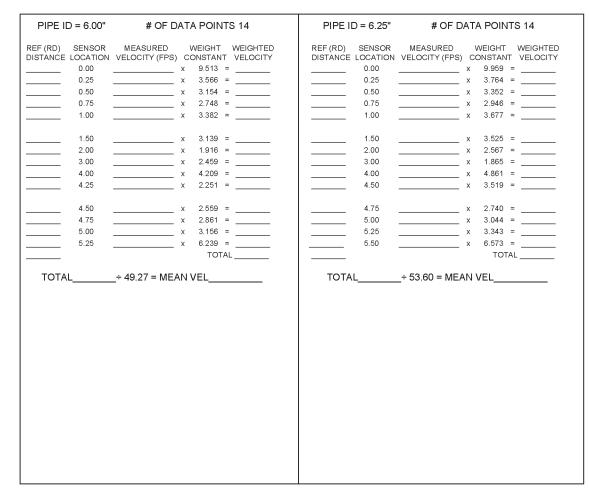
PIPE ID = 4.50"	# OF DATA POINTS 11	PIPE ID = 4.75"	# OF DATA POINTS 12
REF (RD) SENSOR DISTANCE LOCATION 0.25 0.50 0.75 1.00 1.50 2.00 3.00 3.25 3.50 3.75	# OF DATA POINTS 11 MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY 	REF (RD) SENSOR DISTANCE LOCATION 0.25 0.50 0.75 1.00 1.50 2.00 3.00 3.25 3.50 3.75 4.00 1.00	# OF DATA POINTS 12 MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY

4-9



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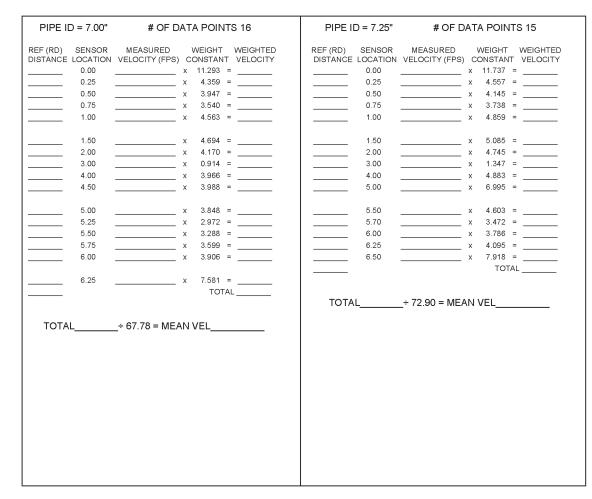
PIPE ID = 5.50" # OF DATA POINTS 1	4 REF (RD) SENSOR MEASURED WEIGHT WEIGHTED
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0.50 x 2.757 =	0.75 x 2.550 =
0.75 x 2.353 =	1.00 x 3.088 =
1.00 x 2.794 =	
	1.50 x 2.754 =
1.50 x 2.371 =	2.00 x 1.362 =
2.00 x 0.904 =	3.00 x 1.827 =
3.00 x 2.402 =	3.50 x 2.880 =
3.50 x 2.253 =	4.00 x 2.986 =
3.75 x 1.897 =	
	4.25 x 2.379 =
4.00 x 2.201 =	4.50 x 2.678 =
4.25 x 2.497 =	4.75 x 2.970 =
4.50 x 2.785 =	5.00 x 5.905 =
4.75 x 5.572 =	TOTAL
TOTAL	
	TOTAL÷ 45.12 = MEAN VEL
TOTAL÷ 41.17 = MEAN VEL	
PIPE ID = 5.75" # OF DATA POINTS 1	4 PIPE ID = 7.50" # OF DATA POINTS 14



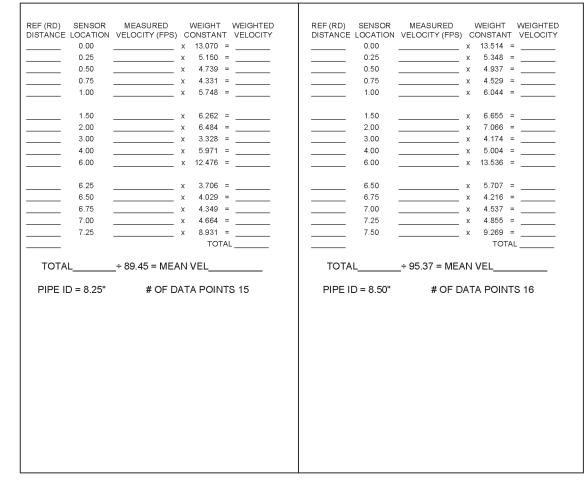
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	STÂNĆE LOCATION VELOCITY (FPS) CONSTANT VELOCITY 0.00 x 10.404 = 0.00 x 10.848 = 0.25 x 3.963 = 0.25 x 4.161 = 0.50 x 3.550 = 0.50 x 3.749 = 0.75 x 3.144 = 0.75 x 3.242 = 1.00 x 3.972 = 1.00 x 4.267 = = 1.50 x 3.914 = 1.50 x 4.267 = = 1.00 x 3.914 = 1.50 x 4.267 = = 1.00 x 3.316 = 2.00 x 4.163 =	PIPE ID = 6.50"	# OF DATA POINTS 15	PIPE ID = 6.75"	# OF DATA POINTS 15
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2.00 x 3.316 = 2.00 x 4.163 = 3.00 x 1.346 = 3.00 x 0.908 = 4.00 x 4.399 = 4.00 x 3.920 = = 4.50 x 3.310 = 4.00 x 3.920 = = 4.50 x 3.310 = 4.50 x 4.291 = = 5.00 x 2.922 = 5.25 x 3.104 = = 5.50 x 3.530 = 5.50 x 3.414 = = 5.75 x 6.908 = 6.00 x 7.244 = = TOTAL TOTAL	2.00 x 3.316 = 2.00 x 4.163 = 3.00 x 1.346 = 3.00 x 0.908 = 4.00 x 4.399 = 4.00 x 3.920 = 4.50 x 3.310 = 4.00 x 3.920 = 4.50 x 3.310 = 4.50 x 4.291 = 4.75 x 2.009 = 5.00 x 4.291 = 5.25 x 3.228 = 5.25 x 3.104 = 5.50 x 3.530 = 5.75 x 3.718 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL TOTAL TOTAL				
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4.00 x 4.399 = 4.00 x 3.920 = 4.50 x 3.310 = 4.50 x 4.291 = 4.75 x 2.609 = 4.50 x 4.291 = 5.00 x 2.922 = 5.25 x 3.104 = 5.50 x 3.530 = 5.50 x 3.414 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL	4.00 x 4.399 = 4.00 x 3.920 =	2.00	x 3.316 =	2.00	x 4.163 =
4.50 x 3.310 = 4.50 x 4.291 = 4.75 x 2.609 = 5.00 x 4.058 = 5.00 x 2.922 = 5.25 x 3.104 = 5.50 x 3.530 = 5.75 x 3.718 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL TOTAL	4.50 x 3.310 =	3.00		3.00	
4.75 x 2.609 = 5.00 x 4.058 = 5.00 x 2.922 = 5.25 x 3.104 = 5.25 x 3.228 = 5.50 x 3.414 = 5.50 x 3.530 = 5.75 x 3.718 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL TOTAL TOTAL TOTAL TOTAL	4.75 x 2.609	4.00	x 4.399 =	4.00	x 3.920 =
5.00 x 2.922 = 5.25 x 3.104 =	5.00 x 2.922 = 5.25 x 3.228 = 5.50 x 3.530 = 5.75 x 6.908 = TOTAL TOTAL	4.50		4.50	x 4.291 =
5.25 x 3.228 = 5.50 x 3.414 = 5.50 x 3.530 = 5.75 x 3.718 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL TOTAL TOTAL TOTAL TOTAL	5.25 x 3.228 = 5.50 x 3.414 = 5.50 x 3.530 = 5.75 x 3.718 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL TOTAL TOTAL TOTAL	4.75		5.00	
5.50 x 3.530 = 5.75 x 3.718 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL TOTAL TOTAL	5.50 x 3.530 = 5.75 x 3.718 = 5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL TOTAL	5.00	x 2.922 =	5.25	x 3.104 =
5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL	5.75 x 6.908 = 6.00 x 7.244 = TOTAL TOTAL				
TOTAL TOTAL	TOTAL TOTAL	5.50	x 3.530 =		
		5.75		6.00	
TOTAL÷ 58.13 = MEAN VEL TOTAL÷ 62.86= MEAN VEL	TOTAL÷ 58.13 = MEAN VEL TOTAL÷ 62.86= MEAN VEL		TOTAL		TOTAL
		TOTAL	_+ 58.13 = MEAN VEL	TOTAL	_+ 62.86= MEAN VEL

4-13



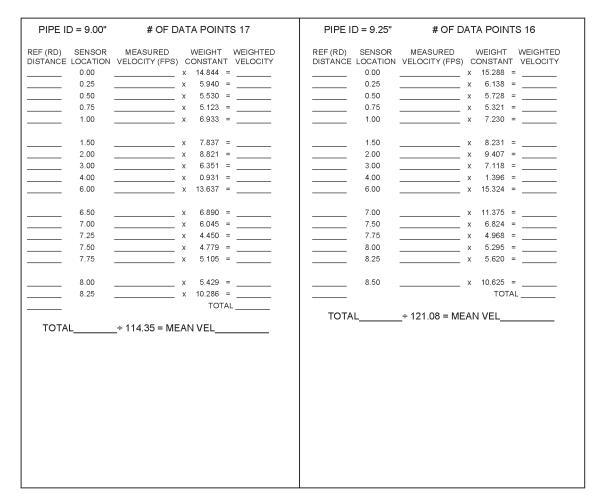
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED
DISTANCE LOCATION VELOCITY (FP S) CONSTANT VELOCITY	DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.00 x 12.182 =	0.00 x 12.626 =
0.25 x 4.754 =	0.25 x 4.952 =
0.50 x 4.343 =	0.50 x 4.541 =
0.75 x 3.936 =	0.75 x 4.133 =
1.00 x 5.155 =	1.00 x 5.451 =
1.50 x 5.477 =	1.50 x 5.869 =
2.00 x 5.323 =	2.00 X 5.902 =
3.00 x 1.929 =	
4.00 x 4.026 =	3.00 x 2.580 = 4.00 x 3.244 =
5.00 x 6.535 =	5.00 x 6.061 =
5.50 x 4.391 =	5.50 x 5.733 =
5.75 x 3.337 =	6.00 x 5.153 =
6.00 x 3.657 =	6.25 x 3.843 =
6.25 x 3.973 =	6.50 x 4.160 =
6.50 x 4.284 =	6.75 x 4.474 =
6.75 x 8.255 = TOTAL	7.00 x 8.593 =
	TOTAL
TOTAL÷ 78.22 = MEAN VEL	TOTAL ÷ 83.73 = MEAN VEL
	PIPE ID = 8.00" # OF DATA POINTS 15
PIPE ID = 7.75" # OF DATA POINTS 16	



8.00 - 8.25

	PIPE ID = 8.75" # OF DATA POINTS 16
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED	
DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED
0.00 x 13.957 =	DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.25 x 5.545 =	0.00 x 14.401 =
0.50 x 5.135 =	0.25 x 5.743 =
0.75 x 4.727 =	0.50 x 5.332 =
1.00 x 6.340 =	0.75 x 4.925 =
	1.00 x 6.637 =
1.50 x 7.049 =	
2.00 x 7.650 =	1.50 x 7.443 =
3.00 x 5.117	2.00 x 8.235 =
=	3.00 x 6.158 =
	4.00 x 3.309 =
6.00 x 12.754 =	6.00 x 11.952 =
6.50 x 5.490 =	6.50 x 7.197 =
6.75 x 4.077 =	7.00 x 6.264 =
7.00 x 4.403 =	7.25 x 4.591 =
7.25 x 4.726 =	7.50 x 4.915 =
7.50 x 5.046 =	7.75 x 5.237 =
7.75 x 9.608 =	8.00 x 9.947 =
	TOTAL
TOTAL ÷ 101.49 = MEAN VEL	TOTAL ÷ 107.82 = MEAN VEL

4-17



4-18

PIPE ID = 9.50"	# OF DATA POINTS 17	PIPE ID = 9.75"	# OF DATA POINTS 17
	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY		MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	x 15.731 =	0.00	x 16.175 =
0.25	x 6.335 =	0.25	x 6.532 =
0.50	x 5.925 =	0.50	x 6.123 =
0.75	x 5.518 =	0.75	x 5.716 =
1.00	x 7.526 =	1.00	x 7.822 =
1.50	x 8.625 =	1.50	x 9.020 =
2.00	x 9.995 =	2.00	x 10.583 =
3.00	x 7.887 =	3.00	x 8.658 =
4.00	x 1.956 =	4.00	x 2.612 =
6.00	x 13.780 =	6.00	x 12.307 =
7.00	x 10.910 =	7.00	x 10.434 =
7.50	x 6.604 =	7.50	x 8.679 =
7.75	x 4.825 =	8.00	x 7.387 =
8.00	x 5.156 =	8.25	x 5.346 =
8.25	x 5.486 =	8.50	x 5.676 =
8.50	x 5.812 =	8.75	x 6.004 =
8.75	x 10.965 =	9.00	x 11.305 =
	TOTAL		TOTAL
TOTAL	_÷ 128.02 = MEAN VEL	TOTAL	_÷ 135.17 = MEAN VEL

4-19

PIPE ID = 10.00"	# OF DATA POINTS 18	PIPE ID = 10.25"	# OF DATA POINTS 17
	ALEASURED WEIGHT WEIGHTED	REF (RD)SENSOR	MEASURED WEIGHT WEIGHTED
	LOCITY (FPS) CONSTANT VELOCITY		VELOCITY (FPS) CONSTANT VELOCITY
	x 16.618 =		x 17.061 =
	x 6.730 =		x 6.927 =
	x 6.320 =		x 6.518 =
	x 5.914 =		x 6.111 =
1.00	x 8.119 =	1.00	x 8.415 =
1.50	x 9.414 =	1.50	x 9.809 =
2.00	x 11.171 =	2.00	x 11.760 =
	x 9.431 =	3.00	x 10.205 =
4.00	x 3.365 =	4.00	x 4.214 =
6.00	x 10.906 =	6.00	x 9.582 =
7.00	x 9.948 =	7.00	x 13.325 =
7.50	x 8.369 =		x 13.604 =
	x 7.164 =		x 7.952 =
8.25	x 5.201 =		x 5.725 =
8.50	x 5.535 =	9.00	x 6.058 =
8.75	x 5.867 =	9.25	x 6.389 =
9.00	x 6.197 =		x 11.985 =
9.25	x 11.645 =		
	TOTAL		
TOTAL ÷ 1	42.53 = MEAN VEL		_÷ 150.10 = MEAN VEL
10 m.c			
		1	

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PIPE ID = 10.50"	# OF DATA POINTS 18	PIPE ID = 10.75" # OF DATA POINTS 18		
	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY		MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	
	x 17.504 =		x 17.947 =	
0.25	x 7.124 =	0.25	x 7.321 =	
0.50	x 6.715 =	0.50	x 6.913 =	
	x 6.309 =	0.75	x 6.506 =	
1.00	x 8.711 =	1.00	x 9.008 =	
1.50	x 10.204 =	1.50	x 10.598 =	
2.00	x 12.349 =	2.00	x 12.939 =	
3.00	x 10.981 =	3.00	x 11.759 =	
4.00	x 5.160 =	4.00	x 6.203 =	
6.00	x 8.336 =	6.00	x 7.171 =	
7.00	x 12.658 =	7.00	x 11.982 =	
8.00	x 13.135 =	8.00	x 12.656 =	
8.50	x 7.727 =	8.50	x 10.175 =	
8.75	x 5.579 =	9.00	x 8.519 =	
9.00	x 5.915 =	9.25	x 6.106 =	
9.25	x 6.250 =	9.50	x 6.441 =	
9.50	x 6.582 =	9.75	x 6.775 =	
9.75	x 12.326 =	10.00	x 12.666 =	
	TOTAL		TOTAL	
TOTAL	_÷ 157.87 = MEAN VEL	TOTAL	_÷ 165.86 = MEAN VEL	

4-21

PIPE ID = 11.00"	# OF DATA POINT	5 19	PIPE ID = 11.2	:5" # OF D/	ATA POINTS 17
		WEIGHTED	REF (RD) SENSC	R MEASURED	WEIGHT WEIGHTE
	LOCITY (FPS) CONSTANT		DISTANCE LOCATIO	ON VELOCITY (FPS)	CONSTANT VELOCITY
	x 18.390 =		0.00		x 18.833 =
			0.25		x 7.716 =
			0.50		x 7.308 =
			0.75		x 6.901 =
1.00	x 9.304 =		1.00		x 9.600 =
1.50	x 10.993 =		1.50		X 11.388 =
	x 13.529 =		1.50 2.00		X 14.119 =
3.00	x 12.537 =		3.00		X 13.317 =
4.00	x 7.345 =		4.00		
6.00	x 6.088 =		6.00		x 9.707 =
7.00	x 11.297 =				×
	x 12.168 =		8.00		X 22.260 =
			9.00		X 15.853 =
			9.50		
9.25	x 5.958 =		9.75		
9.50	x 6.297 =		10.05		7.101
			10.25		x 7.161 =
			10.50		X 13.347 =
	x 13.007 =				TOTAL
		L	TOTAL	÷ 182.47 = ME	AN VEL
ioial÷	174.06 = MEAN VEL				

PIPE ID = 11.50" # OF DATA POINTS 18	PIPE ID = 11.75" # OF DATA POINTS 18
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY 0.00 X 19.276 0.25 X 7.913 = 0.50 X 7.505 = 0.75 X 7.099 = 1.00 X 9.896 =	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY 0.00 X 19.719 = 0.25 X 19.719 = 0.50 X 19.702 = 0.50 X 7.702 =
3.00 X 14.097 =	3.00 X 14.878 =
4.00 x 9.920 =	4.00 X 11.355 =
6.00 x 8.437 =	6.00 x 7.252 =
8.00 X 21.252 = 9.00 X 15.379 = 9.50 X 8.860 = 9.75 X 6.338 = 10.00 X 6.679 = 10.25 X 7.017 = 10.50 X 7.354 = 10.75 X 13.688 = TOTAL	8.00 X 20.231 = 9.00 X 14.896 = 9.50 X 11.681 = 10.00 X 9.659 = 10.25 X 6.870 = 10.50 X 7.210 = 10.75 X 7.548 = 11.00 X 14.029 = TOTAL TOTAL
TOTAL÷ 191.09 = MEAN VEL	TOTAL÷ 199.93 = MEAN VEL

4-23

PIPE ID = 12.00" # OF DATA POINTS 19			PIPE ID = 12.25" # OF DATA POINTS 18			
EF (RD) SENSOR	MEASURED WEIGHT VELOCITY (FPS) CONSTANT		REF (RD) SENSOR DISTANCE LOCATION	MEASURED VELOCITY (FPS)	WEIGHT CONSTANT	
	· · · · · · · · · · · · · · · · · · ·			×		
			0.25	x		
	x 7.899 =		0.50	x	8.097 =	
	x 7.494 =			x		
	X 10.489 =		1.00	X	10.785 =	
1.50	X 12.572 =		1.50	×	12.967 =	
2.00	X 15.890 =		2.00	X	16.481 =	
3.00	X 15.660 =		3.00	X	16.443 =	
4.00	X 12.888 =		4.00	X	14.519 =	
6.00	x 6.153 =		6.00	x	5.141 =	
8.00	X 19.198 =		8.00	x	18.155 =	
9.00	X 14.406 =		9.00	X	19.273 =	
9.50	X 11.365 =		10.00	X	18.116 =	
10.00	x 9.428 =		10.50	X	10.230 =	
10.25	x 6.719 =		10.75	×	7.253 =	
10.50	x 7.061 =		11.00	×	7.595 =	
	x 7.402 =		11.25	X	7.935 =	
11.00	x 7.741 =		11.50	X	14.712 =	
11.25	X 14.371 =				τοτα	L
	TOTAL					
			TOTAL	_÷ 218.24 = MEA	N VEL	
TOTAL	÷ 208.98 = MEAN VEL					

PIPE ID = 13.00"	# OF DATA POINTS 20	PIPE ID = 13.25" # OF DATA POINTS 18				
	SURED WEIGHT WEIGHTED		ASURED WEIGHT WEIGHTEL			
	CITY (FPS) CONSTANT VELOCITY X 21.932 =		CITY (FPS) CONSTANT VELOCITY X 22.375 =			
	X 21.932 = x 9.095 =		X 22.373 =			
	X 8.688 =		x 8.885 =			
	X 8.283 =		x 8.480 =			
	X 11.673 =		X 11.969 =			
1.50	X 14.151 =	1.50	X 14.546 =			
	X 18.254 =		X 18.845 =			
	X 18.794 =		X 19.578 =			
	X 16.564 =		X 17.727 =			
	x 3.389 =		x 4.240 =			
8.00	X 17.571 =	8.00	X 23.448 =			
	X 17.245 =		X 31.225 =			
10.00	X 16.659 =		X 20.392 =			
10.50	X 12.877 =	11.50	X 11.378 =			
11.00	X 10.570 =	11.75	x 8.022 =			
11.25	x 7.484 =	12.00	x 8.367 =			
	x 7.829 =		x 8.710 =			
11.75	x 8.174 =	12.50	X 16.078 =			
12.00	x 8.516 =		TOTAL			
12.25	X 15.736 =					
	TOTAL	TOTAL÷ 25	7.46 = MEAN VEL			
TOTAL÷ 247	.33 = MEAN VEL					

PIPE ID = 13.50" # OF DATA POINTS 19	PIPE ID = 13.75" # OF DATA POINTS 19
PIPE ID = 13.50" # OF DATA POINTS 19 REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	PIPE ID = 13.75" # OF DATA POINTS 19 REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
3.00 X 20.363 = 4.00 X 18.891 = 6.00 X 5.189 = 10.00 X 20.467 = 11.00 X 30.212 = 11.50 X 11.142 =	3.00 X 21.148 = 4.00 X 20.057 = 6.00 X 6.234 = 10.00 X 29.189 = 11.00 X 19.419 = 11.50 X 14.719 =
12.75 X 16.419 = TOTAL TOTAL ÷ 267.80 = MEAN VEL	13.00 X 16.761 = TOTAL TOTAL÷ 278.36 = MEAN VEL

13.50 - 13.75

PIPE ID = 14.00"	# OF DATA POINTS 20	PIPE ID = 14.25" # OF DATA POINTS				
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY			
0.00	X 23.703 =	0.00	X 24.145 =			
0.25	x 9.882 =	0.25	X 10.079 =			
0.50	x 9.477 =	0.50	x 9.674 =			
0.75	x 9.072 =	0.75	x 9.269 =			
	X 12.856 =	1.00	X 13.152 =			
1.50	X 15.730 =	1.50	X 16.125 =			
	X 20.618 =		X 21.210 =			
3.00	X 21.934 =	3.00	X 22.720 =			
	X 21.224 =		X 22.392 =			
6.00	x 7.376 =	6.00	x 8.615 =			
8.00	X 17.722 =	8.00	X 15.981 =			
	X 28.157 =	10.00	X 27.116 =			
11.00	X 18.924 =	11.00	X 25.296 =			
11.50	X 14.397 =	12.00	X 22.678 =			
12.00	X 11.716 =	12.50	X 12.529 =			
12.25	x 8.251 =	12.75	x 8.792 =			
12.50	x 8.600 =	13.00	x 9.140 =			
	x 8.947 =	13.25	x 9.487 =			
13.00	x 9.293 =	13.50	X 17.445 =			
13.25	X 17.103 =		TOTAL			
	TOTAL	TOTAL	÷ 300.14 = MEAN VEL			
τοται	÷ 289.14 = MEAN VEL		- 500.14 - MEAN VEL			

PIPE ID = 14.50'	# OF DATA POINTS 20	PIPE ID = 14.75" # OF DATA POINTS 20
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.00	X 24.588 =	0.00 X 25.030 =
0.25	X 10.276 =	0.25 X 10.473 =
0.50	x 9.871 =	0.50 X 10.068 =
0.75	x 9.466 =	0.75 x 9.663 =
1.00	X 13.448 =	1.00 X 13.744 =
1.50	X 16.519 =	1.50 X 16.914 =
2.00	X 21.801 =	2.00 X 22.392 =
3.00	X 23.506 =	3.00 X 24.292 =
4.00	X 23.561 =	4.00 X 24.732 =
6.00	x 9.179 =	6.00 X 11.386 =
8.00	X 14.325 =	8.00 X 12.755 =
10.00	X 26.066 =	10.00 X 25.009 =
11.00	X 24.623 =	11.00 X 23.943 =
12.00	X 22.191 =	12.00 X 21.697 =
12.50	X 12.290 =	12.50 X 16.248 =
12.75	x 8.636 =	13.00 X 13.106 =
13.00	x 8.985 =	13.25 x 9.179 =
13.25	x 9.334 =	13.50 x 9.528 =
13.50	x 9.682 =	13.75 x 9.876 =
13.75	X 17.786 =	14.00 X 18.128 =
	TOTAL	TOTAL
TOTAL	_÷ 311.35 = MEAN VEL	TOTAL÷ 322.78 = MEAN VEL
		<u> </u>

4-29

PIPE ID = 15.00" # OF DATA POINTS 21				PIPE I	PIPE ID = 15.25" # OF DATA POINTS 19				
REF (RD) S	ENSOR	MEASURED	WEIGHT	WEIGHTED	REF (RD)	SENSOR	MEASURED	WEIGHT	WEIGHTED
		VELOCITY (FPS)			DISTANCE		VELOCITY (FPS)		
						0.00			
						0.25			
	0.75 _		x 9.860 =	·		0.75		X 10.058 =	
	1.00 _		X 14.040 =	=		1.00		X 14.335 =	•
	1.50 _		X 17.308 =	·		1.50		X 17.703 =	·
	2.00 _		X 22.984 =	=		2.00		X 23.575 =	:
	3.00 _		X 25.079 =	=		3.00		X 25.865 =	:
	4.00 _		X 25.903 =						
	6.00		X 12.917 =	•		6.00			
	8.00		X 11.274 =	·		8.00		x 9.881 =	
						10.00			
1									
1	2.00		X 21.199 =			13.00		X 24.972 =	
1	2.50		X 15.922 =	·		13.50		X 13.683 =	·
1	3.00 _		X 12.866 =	:		13.75		x 9.565 =	
1	3.25 _		x 9.021 =	·		14.00		x 9.916 =	
1	3.50		x 9.372 =	=		14.25		X 10.265 =	
1	3.75		x 9.722 =			14.50		X 18.812 =	- <u> </u>
1	4.00 _		X 10.071 =	·				τοτα	L
1	4.25 _		X 18.470 =	·	τοτα	L <u>.</u>	-+ 346.30 = ME	AN VEL	
			ΤΟΤΑ	.L					
TOTAL_		÷ 334.43 = ME/	AN VEL						

PIPE ID = 15.50'	# OF DATA POINTS 20	PIPE ID = 15.75"	# OF DATA POINTS 20
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	X 26.357 =	0.00	X 26.800 =
0.25	X 11.063 =	0.25	X 11.260 =
0.50	X 10.659 =	0.50	X 10.855 =
0.75	X 10.255 =	0.75	X 10.452 =
1.00	X 14.631 =	1.00	X 14.927 =
1.50	X 18.097 =	1.50	X 18.492 =
2.00	X 24.166 =	2.00	X 24.758 =
3.00	X 26.652 =	3.00	X 27.439 =
4.00	X 28.247 =	4.00	X 29.420 =
6.00	X 16.274 =	6.00	X 18.100 =
8.00	x 8.577 =	8.00	x 7.364 =
10.00	X 32.044 =	10.00	X 30.605 =
12.00	X 39.267 =	12.00	X 38.239 =
13.00	X 24.481 =	13.00	X 23.984 =
13.50	X 13.442 =	13.50	X 17.781 =
13.75	x 9.406 =	14.00	X 14.261 =
14.00	x 9.758 =	14.25	x 9.952 =
14.25	X 10.110 =	14.50	X 10.304 =
14.50	X 10.460 =		X 10.655 =
14.75	X 19.155 =	15.00	X 19.497 =
	TOTAL		TOTAL
TOTAL	_÷ 358.39 = MEAN VEL	TOTAL	_÷ 370.69 = MEAN VEL

4-31

PIPE ID = 16.00"	# OF DATA POINTS 21	PIPE ID = 16.25" # OF DATA POINTS 20				
REF (RD) SENSOR		REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY				
	N VELOCITY (FPS) CONSTANT VELOCITY	0.00 X 27.685 =				
0.00	X 27.242 =	0.25 X 11.654 =				
0.25	X 11.457 =	0.50 X 11.249 =				
0.50	X 11.052 =	0.75 X 10.846 =				
0.75	X 10.649 =	1.00 X 15.518 =				
1.00	X 15.222 =					
1.50	X 18.886 =	1.50 X 19.280 =				
2.00	X 25.349 =	2.00 X 25.940 =				
3.00	X 23.349	3.00 X 29.013 =				
4.00	X 20.220	4.00 X 31.768 =				
		6.00 X 22.044 =				
6.00	X 20.023 =					
8.00	x 6.241 =	8.00 x 5.209 =				
10.00	X 29.159 =	10.00 X 27.707 =				
12.00	X 37.203 =	12.00 X 36.159 =				
	X 23.482 =	13.00 X 31.373 =				
13.00 13.50	X 20.402 =	14.00 X 27.273 =				
10.00	X 11.400					
14.00	X 14.019 =	14.50 X 14.840 =				
14.25	x 9.792 =	14.75 X 10.339 =				
14.50	X 10.145 =	15.00 X 10.692 =				
14.75	X 10.498 =	15.25 X 11.044 =				
15.00	X 10.849 =	15.50 X 20.181 =				
		TOTAL				
15.25	X 19.839 =					
	TOTAL	TOTAL÷ 395.96 = MEAN VEL				
TOTAL	÷ 383.22 = MEAN VEL					

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PIPE ID = 16.50" # OF DATA POINTS 21	PIPE ID = 16.75" # OF DATA POINTS 21
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.00 X 28.127 =	0.00 X 28.569 =
0.25 X 11.851 =	0.25 X 12.047 =
0.50 X 11.446 =	0.50 X 11.643 =
0.75 X 11.043 =	0.75 X 11.240 =
1.00 X 15.814 =	1.00 X 16.109 =
1.50 X 19.675 =	1.50 X 20.069 =
2.00 X 26.531 =	2.00 X 27.123 =
3.00 X 29.800 =	3.00 X 30.588 =
4.00 X 32.943 =	4.00 X 34.118 =
6.00 X 24.164 =	6.00 X 26.382 =
8.00 x 4.269 =	8.00 x 3.421 =
10.00 X 26.248 =	10.00 X 24.782 =
12.00 X 35.109 =	12.00 X 34.052 =
13.00 X 30.693 =	13.00 X 30.009 =
14.00 X 26.778 =	14.00 X 26.278 =
14.50 X 14.597 =	14.50 X 19.319 =
14.75 X 10.178 =	15.00 X 15.420 =
15.00 X 10.533 =	15.25 X 10.727 =
15.25 X 10.886 =	15.50 X 11.081 =
15.50 X 11.239 =	15.75 X 11.434 =
15.75 X 20.524 =	16.00 X 20.866 =
TOTAL	TOTAL
TOTAL÷ 408.92 = MEAN VEL	TOTAL÷ 422.10 = MEAN VEL
L	1

PIPE ID = 17.00" # OF DATA POINTS 22				S 22	PIPE ID	PIPE ID = 17.25" # OF DATA POINTS 2				
REF (RD)	SENSOR	MEASURED	WEIGHT	WEIGHTED	REF (RD)	SENSOR	MEASURED	WEIGHT	WEIGHTED	
DISTANCE		VELOCITY (FPS)			DISTANCE		VELOCITY (FPS)			
	0.00					0.00				
	0.25									
	1.00		X 16.405 =			1.00		X 16.700 =	=	
	1.50		X 20.463 =			1.50		X 20.858 =		
	2.00		X 27.714 =			2.00		X 28.305 =		
	3.00					3.00		X 32.163 =		
	4.00		X 35.294 =			4.00		X 36.470 =		
	6.00		X 25.244 =			6.00		X 26.794 =		
	8.00		x 3.425 =			8.00		x 4.283 =		
	10.00		X 25.955 =			10.00		X 23.824 =		
	12.00		X 32.988 =			12.00		X 45.545 =	-	
	13.00		X 29.319 =			14.00		X 49.418 =	-	
	14.00		X 25.773 =			15.00		X 29.580 =	-	
	14.50		X 18.988 =			15.50		X 16.000 =	=	
	15.00		X 15.175 =			15.75		X 11.114 =		
	15.25		X 10.565 =			16.00		X 11.469 =	=	
	15.75		X 11.275 =					X 21.551 =	-	
	16.00		X 11.629 =					TOTA	L	
	16.25		X 21.208 =		ΤΟΤΑΙ	_	÷ 449.11 = ME	AN VEL		
			τοτα	L			-			
τοτα	I	÷ 435.50 = ME	AN VEI							

PIPE ID = 17.50" # OF DATA POINTS 21	PIPE ID = 17.75" # OF DATA POINTS 21
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY 0.00 X 29.896 = 0.25 X 12.637 = 0.50 X 12.234 = 0.75 X 11.831 =	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY 0.00 X 30.338 = 0.25 X 12.834 = 0.50 X 12.430 = 0.75 X 12.027 =
1.00 X 16.996 =	1.00 X 17.291 =
1.50 X 21.252 = 2.00 X 28.897 = 3.00 X 32.950 = 4.00 X 37.646 = 6.00 X 28.346 =	1.50 X 21.646 = 2.00 X 29.488 = 3.00 X 33.738 = 4.00 X 38.823 = 6.00 X 29.899 =
8.00 x 5.237 = 10.00 X 21.780 = 12.00 X 44.117 = 14.00 X 48.391 = 15.00 X 29.081 =	8.00 x 6.288 = 10.00 X 19.824 = 12.00 X 42.682 = 14.00 X 47.357 = 15.00 X 28.578 =
15.50 X 15.754 = 15.75 X 10.952 = 16.00 X 11.308 = 16.25 X 11.664 = 16.50 X 12.019 =	15.50 X 20.859 = 16.00 X 16.580 = 16.25 X 11.502 = 16.50 X 11.858 = 16.75 X 12.214 =
16.75 X 21.893 = TOTAL	17.00 X 22.236 = TOTAL
TOTAL÷ 462.95 = MEAN VEL	TOTAL÷ 476.99 = MEAN VEL

EF (RD) SENSOR		REF (RD) SENSOR	MEASURED	WEIGHT WEIGHTED
	VELOCITY (FPS) CONSTANT VELOCITY	DISTANCE LOCATION	VELOCITY (FPS)	CONSTANT VELOCITY
0.00	X 30.781 =	0.00		X 31.223 =
0.25	X 13.031 =	0.25		X 13.227 =
0.50	X 12.627 =	0.50		X 12.824 =
0.75	X 12.224 =	0.75		X 12.421 =
1.00	X 17.587 =	1.00	:	X 17.882 =
1.50	X 22.040 =	1.50		X 22.435 =
2.00	X 30.079 =			X 30.670 =
3.00	X 34.525 =			X 35.313 =
4.00	X 40.001 =			X 41.178 =
6.00	X 31.454 =			X 33.010 =
8.00	x 7.435 =			0.000 -
10.00	X 17.957 =	8.00	-	x 8.680 =
12.00	X 41.239 =			X 16.180 =
14.00	X 46.315 =			X 39.791 =
15.00	X 28.070 =	14.00		X 45.268 = X 37.488 =
15.50	X 20.526 =			
16.00	X 16.333 =			X 31.892 =
16.25	X 11.339 =			X 17.161 =
16.50	X 11.697 =			X 11.891 =
16.75	X 12.053 =			X 12.248 =
	// 121000	17.25		X 12.604 =
17.00	X 12.409 =	17.50		X 22.921 =
17.25	X 22.578 =			TOTAL
	TOTAL	тота	÷ 505 74 - ME	AN VEL
TOTAL	÷ 491.26 = MEAN VEL		<u>-</u> + 505.74 - WIL7	

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PIPE ID = 18.50" # OF DATA POINTS 22	PIPE ID = 18.75" # OF DATA POINTS 22
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.00 X 31.665 =	0.00 X 32.107 =
0.25 X 13.424 =	0.25 X 13.621 =
0.50 X 13.021 =	0.50 X 13.218 =
0.75 X 12.618 =	0.75 X 12.815 =
1.00 X 18.178 =	1.00 X 18.473 =
1.50 X 22.829 =	1.50 X 23.223 =
2.00 X 31.261 =	2.00 X 31.852 =
3.00 X 36.101 =	3.00 X 36.888 =
4.00 X 42.356 =	4.00 X 43.534 =
6.00 X 34.566 =	6.00 X 36.124 =
8.00 X 10.022 =	8.00 X 11.461 =
10.00 X 14.493 =	10.00 X 12.897 =
12.00 X 38.337 =	12.00 X 36.877 =
14.00 X 44.214 =	14.00 X 43.155 =
15.00 X 36.803 =	15.00 X 36.113 =
16.00 X 31.389 =	16.00 X 30.883 =
16.50 X 16.913 =	16.50 X 22.403 =
16.75 X 11.727 =	17.00 X 17.742 =
17.00 X 12.085 =	17.25 X 12.279 =
17.25 X 12.442 =	17.50 X 12.637 =
17.50 X 12.799 =	17.75 X 12.994 =
17.75 X 23.263 =	18.00 X 23.606 =
TOTAL	TOTAL
TOTAL ÷ 520.44 = MEAN VEL	TOTAL ÷ 535.36 = MEAN VEL
	l.

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PIPE ID = 19.00"	# OF DATA POINTS 23	PIPE ID = 19.25"	# OF DATA POINTS 21
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	X 32.549 =	0.00	X 32.992 =
0.25	X 13.817 =	0.25	X 14.014 =
0.50	X 13.414 =	0.50	X 13.611 =
0.75	X 13.012 =	0.75	X 13.209 =
1.00	X 18.769 =	1.00	X 19.064 =
1.50	X 23.617 =	1.50	X 24.011 =
2.00	X 32.444 =	2.00	X 33.035 =
3.00	X 37.676 =	3.00	X 38.464 =
4.00	X 44.712 =	4.00	X 45.890 =
6.00	X 37.683 =	6.00	X 39.242 =
8.00	X 12.997 =	8.00	X 14.631 =
10.00	X 11.392 =	10.00	x 9.978 =
12.00	X 35.412 =	12.00	X 33.943 =
14.00	X 42.090 =	14.00	X 57.690 =
15.00	X 35.419 =	16.00	X 58.603 =
16.00	X 30.373 =	17.00	X 34.208 =
16.50	X 22.068 =		X 18.324 =
17.00	X 17.494 =	17.75	X 12.668 =
17.25	X 12.115 =	18.00	X 13.027 =
17.50	X 12.474 =	18.25	X 13.385 =
17.75	X 12.832 =	18.50	X 24.291 =
18.00	X 13.190 =		TOTAL
18.25	X 23.948 =		
	TOTAL	TOTAL	_÷ 565.83 = MEAN VEL
τοται	÷ 550.49 = MEAN VEL		
101//L	_ 000.40 - WE/WVVEL		

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PIPE ID = 19.50"	# OF DATA POINTS 22	PIPE ID = 19.75"	# OF DATA POINTS 22
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	X 33.434 =	0.00	X 33.876 =
0.25	X 14.211 =	0.25	X 14.407 =
0.50	X 13.808 =	0.50	X 14.005 =
0.75	X 13.406 =	0.75	X 13.602 =
1.00	X 19.359 =	1.00	X 19.655 =
1.50	X 24.405 =		X 24.799 =
2.00	X 33.626 =	2.00	X 34.217 =
3.00	X 39.252 =	3.00	X 40.040 =
4.00	X 47.069 =	4.00	X 48.248 =
6.00	X 40.803 =	6.00 _	X 42.364 =
8.00	X 16.362 =	8.00	X 18.191 =
10.00	x 8.657 =		x 7.428 =
12.00	X 32.468 =	12.00	X 30.989 =
14.00	X 56.261 =	14.00	X 54.825 =
16.00	X 57.568 =	16.00 _	X 56.526 =
17.00	X 33.702 =	17.00	X 33.193 =
17.50	X 18.074 =	17.50	X 23.949 =
17.75	X 12.503 =	18.00	X 18.906 =
18.00	X 12.862 =		X 13.057 =
18.25	X 13.221 =	18.50	X 13.416 =
18.50	X 13.580 =	18.75	X 13.775 =
18.75	X 24.634 =	19.00	X 24.976 =
	TOTAL		TOTAL
TOTAL	_÷ 581.39 = MEAN VEL	TOTAL	÷ 597.16 = MEAN VEL

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PIPE ID = 20.00" # OF DATA POINTS 23	PIPE ID = 20.25" # OF DATA POINTS 22
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.00 X 34.318 =	0.00 X 34.760 =
0.25 X 14.604 =	0.25 X 14.801 =
0.50 X 14.201 =	0.50 X 14.398 =
0.75 X 13.799 =	0.75 X 13.996 =
1.00 X 19.950 =	1.00 X 20.245 =
1.50 X 25.193 =	1.50 X 25.587 =
2.00 X 34.808 =	2.00 X 35.399 =
3.00 X 40.827 =	3.00 X 41.615 =
4.00 X 49.427 =	4.00 X 50.606 =
6.00 X 43.926 =	6.00 X 45.489 =
8.00 X 20.118 =	8.00 X 22.142 =
10.00 x 6.292 =	10.00 x 5.250 =
12.00 X 29.506 =	12.00 X 28.019 =
14.00 X 53.384 =	14.00 X 51.937 =
16.00 X 55.479 =	16.00 X 54.427 =
17.00 X 32.680 =	17.00 X 43.632 =
17.50 X 23.612 =	18.00 X 36.527 =
18.00 X 18.656 =	18.50 X 19.488 =
18.25 X 12.891 =	18.75 X 13.446 =
18.50 X 13.251 =	19.00 X 13.806 =
18.75 X 13.611 =	19.25 X 14.166 =
19.00 X 13.971 =	19.50 X 25.662 =
19.25 X 25.319 =	TOTAL
TOTAL	
	TOTAL÷ 629.34 = MEAN VEL
TOTAL÷ 613.15 = MEAN VEL	

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PIPE ID = 20.50"	# OF DATA POINTS 23	PIPE ID = 20.75"	# OF DATA POINTS 23
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION VI	MEASURED WEIGHT WEIGHTED ELOCITY (FPS) CONSTANT VELOCITY
0.00	X 35.202 =	0.00	X 35.645 =
0.25	X 14.997 =	0.25	X 15.194 =
0.50	X 14.595 =	0.50	X 14.792 =
0.75	X 14.193 =	0.75	X 14.390 =
1.00	X 20.541 =	1.00	X 20.836 =
1.50	X 25.981 =	1.50	X 26.375 =
2.00	X 35.990 =	2.00	X 36.581 =
3.00	X 42.403 =	3.00	X 43.191 =
4.00	X 51.785 =	4.00	X 52.964 =
6.00	X 47.052 =	6.00	X 48.616 =
8.00	X 24.265 =	8.00	X 26.485 =
10.00	x 4.301 =	10.00	x 3.445 =
12.00	X 26.529 =	12.00	X 25.034 =
14.00	X 50.484 =	14.00	X 49.027 =
16.00	X 53.369 =	16.00	X 52.306 =
17.00	X 42.941 =	17.00	X 42.247 =
18.00	X 36.019 =	18.00	X 35.507 =
18.50	X 19.237 =	18.50	X 25.498 =
18.75	X 13.279 =	19.00	X 20.071 =
19.00	X 13.641 =	19.25	X 13.835 =
19.25	X 14.001 =	19.50	X 14.196 =
19.50	X 14.361 =	19.75	X 14.557 =
19.75	X 26.004 =	20.00	X 26.347 =
	TOTAL		TOTAL
TOTAL	_÷ 645.75 = MEAN VEL	TOTAL÷	662.37 = MEAN VEL

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0.00	JRED WEIGHT WEIGHTED Y (FPS) CONSTANT VELOCITY X 36.087 = X 15.391 = X 14.988 = X 14.586 = X 21.131 = X 26.769 = X 26.769 = X 37.172 = X 43.979 = X 50.180 =	DISTANCE LOCATION VEL 0.00 0.25 0.50 0.75 0.75 0.75 1.00 0.00 0.00 1.50 0.00 0.00 1.50 0.00 0.00 1.50 0.00 0.00 1.50 0.00 0.00 1.00 0.00 0.00	MEASURED WEIGHT WEIGHTED .OCITY (FPS) CONSTANT VELOCITY X 36.529 = X 15.587 = X 15.185 = X 14.783 = X 21.426 = X 27.163 = X 37.763 = X 44.766 = X 55.324 =
0.25 0.50 0.75 1.00 2.00 3.00 4.00 6.00 8.00	X 15.391 = X 14.988 = X 14.586 = X 21.131 = X 26.769 = X 37.172 = X 43.979 = X 54.144 =	0.25 0.50 0.75 1.00 1.50 2.00 3.00 4.00	X 15.587 = X 15.185 = X 14.783 = X 21.426 = X 27.163 = X 37.763 = X 44.766 =
0.50	X 14.988 = X 14.586 = X 21.131 = X 26.769 = X 37.172 = X 43.979 = X 54.144 =	0.50 0.75 1.00 1.50 2.00 3.00 4.00	X 15.185 = X 14.783 = X 21.426 = X 27.163 = X 27.763 = X 37.763 = X 44.766 =
0.75 1.00 2.00 3.00 4.00 6.00 8.00	X 14.586 = X 21.131 = X 26.769 = X 37.172 = X 43.979 = X 54.144 =	0.75 1.00 1.50 2.00 3.00 4.00	X 14.783 = X 21.426 = X 27.163 = X 37.763 = X 44.766 =
1.00 1.50 2.00 3.00 4.00 6.00 8.00	X 21.131 = X 26.769 = X 37.172 = X 43.979 = X 54.144 =	1.00 1.50 2.00 3.00 4.00	X 21.426 = X 27.163 = X 37.763 = X 44.766 =
1.50 2.00 3.00 4.00 6.00 8.00	X 26.769 = X 37.172 = X 43.979 = X 54.144 =	1.50 2.00 3.00 4.00	X 27.163 = X 37.763 = X 44.766 =
2.00	X 37.172 = X 43.979 = X 54.144 =	2.00 3.00 4.00	X 37.763 = X 44.766 =
3.00 4.00 6.00 8.00	X 43.979 = X 54.144 =	2.00 3.00 4.00	X 44.766 =
4.00 6.00 8.00	X 54.144 =	3.00 4.00	X 44.766 =
6.00		4.00	
8.00	X 50.180 =		
			X 51.745 =
10.00	X 25.336 =	8.00	X 26.886 =
10.00	x 3.448 =		x 4.310 =
12.00	X 26.206 =		X 24.043 =
14.00	X 47.565 =		X 46.098 =
16.00	X 51.239 =		X 69.895 =
17.00	X 41.548 =	18.00	X 67.827 =
	X 34.992 =		X 38.850 =
	X 25.158 =		X 20.654 =
	X 19.819 =		X 14.225 =
19.25	X 13.668 =		X 14.586 =
19.50	X 14.030 =	20.25	X 14.948 =
	X 14.391 =		X 27.033 =
	X 14.752 =	20.00	X 27.000 = TOTAL
	X 26.690 =		
	TOTAL	TOTAL÷6	96.23 = MEAN VEL
TOTAL ÷ 679.2	0 = MEAN VEL		

PIPE ID = 21.50" # OF DATA POINTS 23	PIPE ID = 21.75" # OF DATA POINTS 23
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED
DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.00 X 36.971 =	0.00 X 37.413 =
0.25 X 15.784 =	0.25 X 15.980 =
0.50 X 15.382 =	0.50 X 15.578 =
0.75 X 14.980 =	0.75 X 15.177 =
1.00 X 21.722 =	1.00 X 22.017 =
1.50 X 27.557 =	1.50 X 27.950 =
2.00 X 38.354 =	2.00 X 38.944 =
3.00 X 45.554 =	3.00 X 46.342 =
4.00 X 56.503 =	4.00 X 57.683 =
6.00 X 53.311 =	6.00 X 54.877 =
00 X 28.437 =	8.00 X 29.989 =
10.00 x 5.268 =	10.00 x 6.323 =
12.00 X 21.970 =	12.00 X 19.989 =
14.00 X 44.627 =	14.00 X 43.152 =
16.00 X 68.463 =	16.00 X 67.026 =
18.00 X 66.784 =	18.00 X 65.736 =
19.00 X 38.339 =	19.00 X 37.824 =
19.50 X 20.401 =	19.50 X 27.048 =
19.75 X 14.057 =	20.00 X 21.237 =
20.00 X 14.419 =	20.25 X 14.614 =
20.25 X 14.781 =	20.50 X 14.977 =
20.50 X 15.143 =	20.75 X 15.338 =
20.75 X 27.376 =	21.00 X 27.719 =
TOTAL	TOTAL
TOTAL÷ 713.47 = MEAN VEL	TOTAL÷ 730.92 = MEAN VEL

PIPE ID = 22.00"	# OF DATA POINTS 24	PIPE ID = 22.25"	# OF DATA POINTS 23
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	X 37.855 =	0.00	X 38.297 =
0.25	X 16.177 =	0.25	X 16.373 =
0.50	X 15.775 =	0.50	X 15.972 =
0.75	X 15.374 =	0.75	X 15.570 =
1.00	X 22.312 =	1.00	X 22.607 =
1.50	X 28.344 =	1.50	X 28.738 =
	X 39.535 =	2.00	X 40.126 =
3.00	X 47.130 =	3.00	X 47.918 =
4.00	X 58.863 =	4.00	X 60.043 =
6.00	X 56.443 =	6.00	X 58.010 =
8.00	X 31.542 =	8.00	X 33.096 =
	x 7.475 =		x 8.724 =
	X 18.099 =	12.00	X 16.302 =
14.00	X 41.673 =	14.00	X 40.191 =
16.00	X 65.583 =	16.00	X 64.135 =
18.00	X 64.683 =	18.00	X 63.626 =
	X 37.307 =		X 49.799 =
19.50	X 26.707 =	20.00	X 41.176 =
20.00	X 20.983 =	20.50	X 21.821 =
20.25	X 14.446 =	20.75	X 15.004 =
20.50	X 14.809 =	21.00	X 15.367 =
	X 15.172 =		X 15.729 =
	X 15.534 =		X 28.404 =
	X 28.061 =		
	TOTAL		
		TOTAL	_÷ 766.44 = MEAN VEL
IOTAL	_÷ 748.58 = MEAN VEL		

PIPE ID = 22.50" # OF DATA POINTS 24	PIPE ID = 22.75" # OF DATA POINTS 24
REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR MEASURED WEIGHT WEIGHTED DISTANCE LOCATION VELOCITY (FPS) CONSTANT VELOCITY
0.00 X 38.739 =	0.00 X 39.181 =
0.25 X 16.570 =	0.25 X 16.767 =
0.50 X 16.168 =	0.50 X 16.365 =
0.75 X 15.767 =	0.75 X 15.964 =
1.00 X 22.902 =	1.00 X 23.198 =
1.50 X 29.132 =	1.50 X 29.526 =
2.00 X 40.717 =	2.00 X 41.308 =
3.00 X 48.705 =	3.00 X 49.493 =
4.00 X 61.223 =	4.00 X 62.403 =
6.00 X 59.577 =	6.00 X 61.145 =
8.00 X 34.651 =	8.00 X 36.207 =
10.00 X 10.070 =	10.00 X 11.513 =
12.00 X 14.597 =	12.00 X 12.985 =
14.00 X 38.705 =	14.00 X 37.215 =
16.00 X 62.683 =	16.00 X 61.226 =
18.00 X 62.563 =	18.00 X 61.496 =
19.00 X 49.103 =	19.00 X 48.403 =
20.00 X 40.662 =	20.00 X 40.145 =
20.50 X 21.566 =	20.50 X 28.600 =
20.75 X 14.835 =	21.00 X 22.404 =
21.00 X 15.199 =	21.25 X 15.394 =
21.25 X 15.562 =	21.50 X 15.757 =
21.50 X 15.925 =	21.75 X 16.121 =
21.75 X 28.747 =	22.00 X 29.090 =
TOTAL	TOTAL
TOTAL÷ 784.50 = MEAN VEL	TOTAL÷ 802.76 = MEAN VEL

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	ISOR MEASURED ATION VELOCITY (FPS)	WEIGHT CONSTANT		REF (RD) SENSOR		WEIGHT WEIGHTED
0.0	, oc	X 39.624 =	:		. ,	CONSTANT VELOCITY
0.2					2	X 17.160 =
0.6						X 17.160 =
0.7	75	X 16.160 =	·			X 16.357 =
1.0	0	X 23.493 =	·			X 23.788 =
1.8	50	X 29.919 =	:	4.50		
2.0						X 30.313 =
3.0						X 42.489 =
4.0						X 51.069 =
6.0		X 62.713 =	·			X 64.764 = X 64.281 =
				8.00	;	X 39.321 =
10.0						X 14.691 =
12.0						X 10.040 =
14.0						X 34.227 =
16.0		X 59.764 =	·			X 58.299 =
18.0		X 60.426 =	:		,	X 82.149 =
19.0		X 47.701 =	·			X 77.082 =
20.0		X 39.626 =	:			X 43.504 =
20.8	50	X 28.257 =	:			X 22.988 =
21.0		X 22.149 =	·	21.75		X 15.784 =
21.2				22.00		X 16.148 =
21.5						X 16.512 =
21.7						X 29.776 =
22.0						TOTAL
22.2						
			L	TOTAL	÷ 839.89 = MEA	N VEL
TOTAL	÷ 821.23 = ME	AN VEL				

REF (RD) SENSOR			# OF DATA POINTS 24
	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	X 40.508 =	0.00	X 40.950 =
0.25	X 17.356 =	0.25	X 17.553 =
0.50	X 16.955 =	0.50	X 17.152 =
0.75	X 16.554 =	0.75	X 16.751 =
1.00	X 24.083 =	1.00	X 24.378 =
1.50	X 30.707 =	1.50	X 31.101 =
2.00	X 43.080 =	2.00	X 43.671 =
3.00	X 51.856 =	3.00	X 52.644 =
4.00	X 65.944 =	4.00	X 67.124 =
6.00	X 65.850 =	6.00	X 67.419 =
8.00	X 40.879 =	8.00	X 42.438 =
10.00	X 16.426 =	10.00	X 18.259 =
12.00	x 8.708 =	12.00	x 7.470 =
14.00	X 32.728 =	14.00	X 31.227 =
16.00	X 56.830 =	16.00	X 55.356 =
18.00	X 80.714 =	18.00	X 79.273 =
20.00	X 76.032 =	20.00	X 74.978 =
21.00	X 42.988 =	21.00	X 42.469 =
21.50	X 22.732 =	21.50	X 30.154 =
21.75	X 15.614 =	22.00	X 23.573 =
22.00	X 15.979 =	22.25	X 16.174 =
22.25	X 16.343 =	22.50	X 16.539 =
22.50	X 16.707 =	22.75	X 16.903 =
22.75	X 30.119 =	23.00	X 30.462 =
	TOTAL		TOTAL
1	÷ 858.75 = MEAN VEL	TOTAL	_÷ 877.81 = MEAN VEL

PIPE ID = 24.00"	# OF DATA POINTS 25	PIPE ID = 24.25" #	OF DATA POINTS 24
EF (RD) SENSOR	MEASURED WEIGHT WEIGHTED	REF (RD) SENSOR MEASU	
	VELOCITY (FPS) CONSTANT VELOCITY	DISTANCE LOCATION VELOCITY	
	X 41.392 =		x 41.834 =
	X 17.749 =		x 17.946 =
	X 17.348 =		x 17.545 =
0.75	X 16.947 =		x 17.144 =
1.00	X 24.673 =	1.00	x 24.969 =
1.50	X 31.494 =	1.50	x 31.888 =
2.00	X 44.261 =	2.00	x 44.852 =
3.00	X 53.432 =	3.00	x 54.220 =
4.00	X 68.305 =	4.00	x 69.485 =
6.00	X 68.988 =	6.00	x 70.557 =
8.00	x 43.998 =	8.00	x 45.558 =
10.00	x 20.189 =		x 22.216 =
12.00	x 6.326 =	12.00	x 5.277 =
14.00	x 29.723 =	14.00	x 28.216 =
16.00	x 53.880 =	16.00	x 52.399 =
18.00	x 77.828 =	18.00	x 76.379 =
20.00	x 73.919 =		x 72.856 =
21.00	x 41.947 =	21.00	x 55.982 =
21.50	x 29.809 =	22.00	x 45.834 =
22.00	x 23.316 =	22.50	x 24.157 =
22.25	x 16.003 =	22.75	x 16.564 =
22.50	x 16.369 =	23.00	x 16.929 =
	x 16.734 =		x 17.294 =
23.00	x 17.099 =		x 31.148 =
23.25	x 30.805 =		TOTAL
	TOTAL		
TOTAL	÷ 897.06 = MEAN VEL	ioial÷916.51	= MEAN VEL

PIPE ID = 24.50"	# OF DATA POINTS 25	PIPE ID = 24.75"	# OF DATA POINTS 25
EF (RD) SENSOR	MEASURED WEIGHT WEIGHTED	REF (RD) SENSOR	MEASURED WEIGHT WEIGHTED
ISTANCE LOCATION	VELOCITY (FPS) CONSTANT VELOCITY	DISTANCE LOCATION	VELOCITY (FPS) CONSTANT VELOCITY
0.00	x 42.276 =	0.00	x 42.718 =
0.25	x 18.142 =	0.25	x 18.339 =
0.50	x 17.741 =	0.50	x 17.938 =
0.75	x 17.341 =	0.75	x 17.537 =
1.00	x 25.264 =	1.00	x 25.559 =
1.50	x 32.282 =	1.50	x 32.675 =
2.00	x 45.442 =	2.00	x 46.033 =
3.00	x 55.007 =	3.00	x 55.795 =
4.00	x 70.665 =	4.00	x 71.846 =
6.00	x 72.127 =	6.00	x 73.697 =
8.00	x 47.119 =	8.00	x 48.680 =
10.00	x 24.341 =	10.00	x 26.564 =
12.00	x 4.322 =	12.00	x 3.462 =
14.00	x 26.707 =	14.00	x 25.196 =
16.00	x 50.916 =	16.00	x 49.429 =
18.00	x 74.925 =	18.00	x 73.467 =
20.00	x 71.789 =	20.00	x 70.718 =
21.00	x 55.282 =	21.00	x 54.578 =
22.00	x 45.316 =	22.00	x 44.794 =
22.50	x 23.900 =	22.50	x 31.709 =
22.75	x 16.393 =	23.00	x 24.741 =
23.00	x 16.759 =	23.25	x 16.954 =
23.25	x 17.125 =	23.50	x 17.320 =
23.50	x 17.490 =	23.75	x 17.685 =
23.75	x 31.491 =		x 31.834 =
	TOTAL		TOTAL
	÷ 936.15 = MEAN VEL		÷ 955.98 = MEAN VEL

4-49

REF (RD) DISTANCE	SENSOR LOCATION	MEASURED VELOCITY (FPS)	WEIGHT CONSTANT		REF (RD) DISTANCE	SENSOR LOCATION	MEASURED VELOCITY (FPS)		WEIGHTED
	0.00		x 43.160 =	:		0.00		x 43.602 =	
	0.25		x 18.536 =			0.25		x 18.732 =	
	0.50		x 18.135 =	-		0.50		x 18.331 =	
	0.75		x 17.734 =	·					
	1.00		x 25.854 =	=		1.00		x 26.149 =	
	1.50		x 33.069 =			1.50		x 33.463 =	
	3.00		x 56.583 =			3.00		x 57.370 =	
	4.00		x 73.026 =	=		4.00		x 74.207 =	
	6.00		x 75.267 =	·		6.00		x 76.837 =	
	8.00		x 50.242 =	·		8.00		x 51.804 =	
	10.00		x 25.408 =			10.00		x 26.959 =	
	12.00		x 3.463 =	· ·		12.00		x 4.328 =	
	14.00		x 26.368 =	·		14.00		x 24.185 =	
	16.00		x 47.940 =	·		16.00		x 46.447 =	
	18.00		x 72.005 =	:					
	20.00		x 69.644 =	·		20.00		x 94.444 =	
	21.00		x 53.872 =	=		22.00		x 86.362 =	
	22.00		x 44.271 =			23.00		x 48.167 =	
	22.50		x 31.363 =	·		23.50		x 25.326 =	
	23.00		x 24.483 =	:		23.75		x 17.345 =	
	23.25		x 16.783 =			24.00		x 17.711 =	
	23.50		x 17.149 =	=		24.25		x 18.077 =	
	23.75		x 17.515 =	=		24.50		x 32.520 =	
	24.00		x 17.881 =	·	——			TOTA	L
	24.25				ТОТА	L	<u>+</u> 996.21 = ME	AN VEL	
тота		÷ 976.00 = ME	τοτρ	L	ΤΟΤΑ	L	_÷ 996.21 = ME	AN VEL	

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PIPE ID = 25.50"	# OF DATA POINTS 25	PIPE ID = 25.75"	# OF DATA POINTS 25
EF (RD) SENSOR	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	x 44.044 =	0.00	x 44.486 =
0.25	x 18.929 =	0.25	x 19.125 =
0.50	x 18.528 =	0.50	x 18.724 =
0.75	x 18.127 =	0.75	x 18.324 =
1.00	x 26.444 =	1.00	x 26.739 =
1.50	x 33.856 =	1.50	x 34.250 =
	x 47.805 =		x 48.395 =
3.00	x 58.158 =	3.00	x 58.945 =
4.00	x 75.388 =	4.00	x 76.568 =
6.00	x 78.408 =	6.00	x 79.979 =
8.00	x 53.367 =	8.00	x 54.930 =
10.00	x 28.510 =	10.00	x 30.063 =
12.00	x 5.290 =	12.00	x 6.348 =
14.00	x 22.095 =	14.00	x 20.098 =
16.00	x 44.952 =	16.00	x 43.454 =
18.00	x 69.070 =	18.00	x 67.598 =
20.00	x 93.004 =	20.00	x 91.560 =
22.00	x 85.305 =	22.00	x 84.245 =
23.00	x 47.646 =	23.00	x 47.122 =
23.50	x 25.067 =	23.50	x 33.265 =
23.75	x 17.173 =	24.00	x 25.911 =
24.00	x 17.540 =	24.25	x 17.735 =
24.25	x 17.906 =	24.50	x 18.102 =
24.50	x 18.273 =		x 18.468 =
24.50	x 32.863 =		x 33.206 =
	TOTAL		TOTAL
			÷ 1037.19 = MEAN VEL

4-51

() -	SENSOR	MEASURED VELOCITY (FPS)	WEIGHT		REF (RD) DISTANCE	SENSOR	MEASURED VELOCITY (FPS)	WEIGHT CONSTANT	WEIGHTEE
	0.50					0.50			
	0.75					0.75			
	1.00		x 27.034	=		1.00		x 27.329 =	·
	1.50		x 34.643	=		1.50		x 35.037 =	
	2.00		x 48.986	=					
	3.00		x 59.733	=		3.00		x 60.520 =	·
	4.00		x 77.749	=		4.00		x 78.929 =	·
	6.00		x 81.549	=		6.00		x 83.120 =	·
	8.00					8.00			
	10.00		x 31.616	=					
	16.00 .		x 41.954	=		16.00		x 40.451 =	·
	18.00		x 66.122	=		18.00		x 64.643 =	·
2	20.00		x 90.112	=		20.00		x 88.660 =	
2	22.00		x 83.181	=		22.00		x 82.113 =	·
2	23.00		x 46.597	=		23.00		x 62.180 =	
2	23.50 .		x 32.917	=		24.00		x 50.501 =	
2						24.50		x 26.496 =	
2									
2									
2	25.00		x 18.664	=		25.50			L
2	25.25			= FAL	τοτα	L	_÷ 1078.89 = M	EAN VEL	
τοται		÷ 1057.95 = MI	EAN VEI						

PIPE ID = 26.50"	# OF DATA POINTS 26	PIPE ID = 26.75"	# OF DATA POINTS 26
REF (RD) SENSOR	MEASURED WEIGHT WEIGHTED	REF (RD) SENSOR	MEASURED WEIGHT WEIGHTED
	VELOCITY (FPS) CONSTANT VELOCITY	DISTANCE LOCATION	VELOCITY (FPS) CONSTANT VELOCITY
	x 45.812 =	0.00	x 46.254 =
	x 19.715 =	0.25	x 19.911 =
	x 19.314 =	0.50	x 19.511 =
	x 18.914 =	0.75	x 19.111 =
1.00 _	x 27.624 =	1.00	x 27.919 =
1.50	x 35.431 =	1.50	x 35.824 =
2.00	x 50.167 =		x 50.757 =
3.00	x 61.308 =		x 60.095 =
4.00	x 80.110 =		x 81.290 =
6.00	x 84.692 =	6.00	x 86.263 =
8.00	x 59.622 =	8.00	x 61.187 =
10.00	x 34.724 =		x 36.279 =
12.00	x 10.105 =		x 30.279 =
14.00	x 14.668 =		x 11.001 =
16.00	x 38.946 =		x 13.545 =
18.00	x 63.160 =	18.00	x 61.675 =
20.00	x 87.204 =		
22.00	x 81.041 =		x 85.745 =
	x 61.475 =		x 79.966 =
	x 49.978 =		x 60.767 = x 49.452 =
24.50	x 26.236 =	24.50	× 24,822 -
24.75	x 17.953 =		x 34.822 =
	x 18.321 =		x 27.081 = _ x 18.516 =
	x 18.688 =		x 18.816
	x 19.055 =	25.50	X 18.884 = X 19.251 =
25.75	x 34.235 =	20.00	× 24570 -
	TOTAL		x 34.579 =
			TOTAL
IOTAL	÷ 1100.01 = MEAN VEL	TOTAL	÷ 1121.31 = MEAN VEL

4-53

PIPE ID = $2i$ REF (RD) SENS	7.00" # OF D.		WEIGHTED	PIPE ID = 27.25" REF (RD) SENSOR	# OF DA	ATA POINTS 25
	TION VELOCITY (FPS)					CONSTANT VELOCITY
0.00	()				()	x 47.138 =
0.2						x 20.304 =
0.50				0.50		x 19.904 =
0.75						x 19.504 =
1.00				1.00		x 28.509 =
1.50	D	x 36.218 =		1.50		x 36.611 =
2.00						x 51.938 =
3.00						x 63.670 =
4.00						x 83.652 =
6.00						x 89.406 =
.00)	x 62.753 =		8.00		x 64.318 =
10.00)	x 37.835 =		10.00		x 39.392 =
12.00)	x 13.095 =		12.00		x 14.736 =
14.00)	x 11.517 =		14.00		x 10.083 =
16.00		x 35.929 =		16.00		x 34.417 =
18.00)	x 60.187 =		18.00		x 58.697 =
20.00)	x 84.281 =		20.00		x 82.815 =
22.00		x 78.888 =		22.00		x 106.771 =
23.00)	x 60.057 =		24.00		x 95.661 =
24.00		x 48.925 =		25.00		x 52.836 =
24.50		x 34.473 =				x 27.666 =
25.00						x 18.907 =
25.2						x 19.275 =
25.50		x 18.711 =		26.25		x 19.643 =
25.75	5	x 19.079 =		26.50		x 35.265 = TOTAL
26.00)	x 19.447 =				
26.25				TOTAL	÷ 1164.43 = ME	EAN VEL
			L		_	
TOTAL	<u>+</u> 1142.78 = M	EAN VEL				

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EF (RD) SENSOR	MEASURED WEIGHT WEIGHTED	REF (RD) SENSOR	MEASURED WEIGHT WEIGHTED
	VELOCITY (FPS) CONSTANT VELOCITY		VELOCITY (FPS) CONSTANT VELOCITY
	x 47.580 =	0.00	x 48.022 =
	x 20.501 =		x 20.697 =
	x 20.100 =	0.50	x 20.297 =
0.75	x 19.700 =	0.75	x 19.897 =
1.00	x 28.804 =	1.00	x 29.099 =
1.50	x 37.005 =	1.50	x 37.398 =
2.00	x 52.528 =	2.00	x 53.119 =
3.00	x 64.458 =	3.00	x 65.245 =
4.00	x 84.832 =	4.00	x 86.013 =
6.00	x 90.978 =	6.00	x 92.550 =
8.00	x 65.884 =	8.00	x 67.451 =
10.00	x 40.949 =	10.00	x 42.507 =
12.00	x 16.474 =	12.00	x 18.310 =
14.00	x 8.744 =	14.00	x 7.500 =
16.00	x 32.903 =	16.00	x 31.388 =
18.00	x 57.203 =	18.00	x 55.708 =
20.00	x 81.345 =	20.00	x 79.872 =
22.00	x 105.328 =	22.00	x 103.880 =
24.00	x 94.598 =	24.00	x 93.532 =
25.00	x 52.311 =	25.00	x 51.784 =
25.50	x 27.405 =	25.50	x 36.380 =
25.75	x 18.733 =	26.00	x 28.252 =
26.00	x 19.102 =	26.25	x 19.298 =
	x 19.471 =		x 19.666 =
26.50	x 19.839 =	26.75	x 20.034 =
26.75	x 35.608 =	27.00	x 35.951 =
	TOTAL		TOTAL
TOTAL	÷ 1186.24 = MEAN VEL	TOTAL	÷ 1208.23 = MEAN VEL

EF (RD) SENSOR	MEASURED WEIGHT VELOCITY (FPS) CONSTANT	WEIGHTED VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED VELOCITY (FPS)	WEIGHT WEIGHTED CONSTANT VELOCITY
0.00	x 48.464 =		0.00	X	48.906 =
0.25	x 20.894 =		0.25	×	21.090 =
0.50	x 20.494 =		0.50		20.690 =
0.75	x 20.094 =		0.75	×	20.290 =
1.00 _	x 29.394 =		1.00	×	29.689 =
1.50	x 37.792 =		1.50	×	38.185 =
2.00	x 53.709 =		2.00	×	54.300 =
3.00	x 66.033 =		3.00	×	66.820 =
4.00	x 87.194 =		4.00	×	88.374 =
6.00	x 94.122 =		6.00	×	95.694 =
8.00	x 69.017 =		8.00	×	70.584 =
10.00	x 44.066 =		10.00	×	45.625 =
12.00	x 20.243 =		12.00	×	22.273 =
14.00	x 6.350 =				5.296 =
16.00	x 29.870 =		16.00	×	28.351 =
18.00	x 54.210 =		18.00	×	52.709 =
	x 78.396 =				76.917 =
	x 102.429 =				: 100.974 =
	x 92.463 =				91.390 =
25.00 _	x 51.255 =		25.00	×	68.389 =
	x 36.030 =				55.173 =
	x 27.990 =				28.837 =
	x 19.124 =				19.688 =
	x 19.493 =				20.057 =
26.75 _	x 19.862 =		27.25	×	20.426 =
	x 20.230 =		27.50	×	36.637 =
27.25	x 36.294 =				TOTAL
	τοται			÷ 1252 70 = ME	AN VEL

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PIPE ID = 28.50"	# OF DATA POINTS 27	PIPE ID = 28.75"	# OF DATA POINTS 27
REF (RD) SENSOR DISTANCE LOCATION V	MEASURED WEIGHT WEIGHTED 'ELOCITY (FPS) CONSTANT VELOCITY	REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	x 49.348 =	0.00	x 49.790 =
	x 21.287 =	0.25	x 21.483 =
0.50		0.50	x 21.083 =
		0.75	x 20.683 =
	x 20.887 =	1.00	x 30.279 =
0.75	x 20.487 =		
	x 29.984 =	1.50	x 38.972 =
		2.00	x 55.480 =
1.50	x 38.579 =	3.00	x 68.395 =
	x 54.890 =	4.00	x 90.736 =
	x 67.608 =	6.00	x 98.838 =
	x 89.555 =		
	x 97.266 =	8.00	x 73.719 =
		10.00	x 48.744 =
8.00	x 72.151 =	12.00	x 26.627 =
	x 47.184 =	14.00	x 3.473 =
	x 24.401 =	16.00	x 25.308 =
	x 4.337 =		
	x 26.830 =	18.00	x 49.702 =
		20.00	x 73.950 =
18.00	x 51.207 =	22.00	x 98.054 =
20.00	x 75.435 =	24.00	x 89.235 =
22.00	x 99.515 =	25.00	x 66.968 =
	x 90.314 =		
	x 67.680 =	26.00	x 54.118 =
			x 37.939 =
26.00	x 54.646 =	27.00	x 29.423 =
	x 28.575 =	27.25	x 20.079 =
	x 19.514 =	27.50	x 20.449 =
	x 19.884 =		
	x 20.253 =	27.75	x 20.818 =
			x 37.324 =
27.50	x 20.622 =		
27.75	x 36.980 =		
	TOTAL	TOTAL	÷ 1297.83 = MEAN VEL

4-57

PIPE ID = 29.00"	# OF DATA POINTS 28	PIPE ID = 29.25"	# OF DATA POINTS 26
REF (RD) SENSOR DISTANCE LOCATION	MEASURED WEIGHT WEIG VELOCITY (FPS) CONSTANT VELO		MEASURED WEIGHT WEIGHTED VELOCITY (FPS) CONSTANT VELOCITY
0.00	x 50.232 =	0.00	x 50.674 =
0.25	x 21.680 =	0.25	x 21.876 =
0.50	x 21.280 =	0.50	x 21.476 =
0.75	x 20.880 =	0.75	x 21.077 =
1.00	x 30.574 =	1.00	x 30.869 =
1.50	x 39.365 =	1.50	x 39.759 =
2.00	x 56.071 =		x 56.661 =
3.00	x 69.182 =		x 69.970 =
4.00	x 91.916 =		x 93.097 =
6.00	x 100.410 =		x 101.983 =
8.00	x 75.286 =	8.00	x 76.854 =
10.00	x 50.305 =	10.00	x 51.866 =
12.00		12.00	x 27.017 =
	x 25.466 =	14.00	x 4.342 =
14.00	x 3.475 =	16.00	x 24.285 =
16.00	x 26.481 =		
		18.00	x 46.686 =
18.00	x 48.195 =	20.00	x 70.973 =
20.00	x 72.463 =	22.00	x 95.120 =
22.00	x 96.589 =	24.00	x 119.127 =
24.00	x 88.154 =	26.00	x 104.975 =
25.00	x 66.255 =		
		27.00	x 57.511 =
26.00	x 53.587 =	27.50	x 30.009 =
26.50	x 37.587 =	27.75	x 20.470 =
27.00	x 29.161 =	28.00	x 20.840 =
27.25	x 19.905 =		x 21.209 =
27.50	x 20.275 =		
		28.50	x 38.010 =
27.75	x 20.644 =		
28.00	x 21.014 =		
28.25	x 37.667 =		_÷ 1343.59 = MEAN VEL

4-58

REF (RD)	SENSOR	MEASURED	WEIGHT	WEIGHTED	REF (RD)	SENSOR	MEASURED	WEIGHT	
DISTANCE	LOCATION	VELOCITY (FPS)	CONSTANT	VELOCITY	DISTANCE		VELOCITY (FPS)		
	0.00		x 51.116 =		——				
	0.25		x 22.073 =		——	0.25			
	0.50		x 21.673 =			0.50			
	0.75		x 21.273 =			0.75			
	1.00		x 31.164 =			1.00		X 31.459 =	=
	1.50		x 40.152 =						
	2.00								
	3.00					3.00			
	4.00					4.00		x 95.458 =	
	6.00					6.00		x 105.128 =	·
	8.00		x 78.422 =			8.00		x 79.990 =	·
	10.00					10.00		x 54.989 =	=
	12.00					12.00		x 30.122 =	·
						14.00		x 6.367 =	·
	16.00					16.00		x 20.175 =	·
	18.00		v 45.175 =			18.00		x 43.663 =	·
						20.00		x 67.987 =	·
						22.00		x 92.175 =	=
						24.00		x 116.228 =	
	26.00					26.00		x 102.836 =	·
	27.00		v 56.983 =			27.00		x 56.452 =	
						27.50		x 39.498 =	:
						28.00		x 30.595 =	
	28.00					28.25		x 20.861 =	
	28.25					28.50		x 21.231 =	
	28.50		V 01405 -			28.75		x 21.601 =	·
	28.50 28.75					29.00		x 38.696 =	
	20.70							ΤΟΤΑ	L

28.00 - 28.25

4-59

PIPE ID = 30.00'	# OF DATA POINTS 28	,	
F (RD) SENSOR		GHTED	
	VELOCITY (FPS) CONSTANT VEL		
0.00	x 52.000 =		
0.25	x 22.466 =		
0.50	x 22.066 =		
0.75	x 21.666 =		
1.00	x 31.754 =		
1.50	x 40.939 =		
2.00	x 58.432 =		
3.00	x 72.331 =		
4.00	x 96.639 =		
6.00	x 106.701 =		
8.00	x 81.559 =		
10.00	x 56.551 =		
12.00	x 31.676 =		
14.00	x 7.524 =		
16.00	x 18.262 =		
18.00	x 42.148 =		
20.00	x 66.490 =		
22.00	x 90.698 =		
24.00	x 114.773 =		
26.00	x 01.762 =		
27.00	x 55.920 =		
27.50	x 39.146 =		
28.00	x 30.331 =		
28.25	x 20.686 =		
28.50	x 21.057 =		
28.75	x 21.427 =		
29.00	x 21.797 =		
29.25	x 39.040 =		

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